# invensus Eurotherm

# 2408i Series Process Indicators User Manual

Part No: HA027240\_5 Date: February 2015

## MODEL 2408/INDICATOR

## **User Manual**

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## 2408/Indicator and Alarm Unit

## 1 Installing and Operating Instructions

Thank you for choosing the 2408*i* panel mounted indicator. It will provide accurate measurement and display of temperature and other process variables. A modular build accepts a wide range of plug-in modules allowing: up to four alarm outputs, two process variable (PV) inputs, direct strain gauge/pressure sensor measurements, custom linearisation, analogue retransmission, remote setpoint (SP) input and digital communications.

The indicator is supplied configured in accordance with the order code. The order code and instrument serial number is shown on a label fixed to the top of the case, and this can be checked against the order code given in section 5 of these instructions.

## 1.1 Contents of package

- 1. A peel-off label set a convenient position is to fix a label to the top right of the display.
- 2. A 2.49 $\Omega$  resistor used as the load resistor for a mA input
- 3. Two panel retaining clips
- 4. Panel sealing gasket

## 1.2 Dimensions and Installation





l/h

cm



## 1.2.1 To Install the Indicator

Please read the safety information in section 6 before proceeding.

The indicator is intended to be mounted on a panel within an enclosure such as a control cubicle.

- 1. Prepare the panel cut-out to the size shown.
- 2. Fit the sealing gasket behind the front bezel of the instrument.
- 3. Insert the indicator in its sleeve through the cut-out.
- 4. Spring the panel retaining clips into place. Secure the indicator in position by holding it level and pushing both retaining clips forward.
- 5. Peel off the plastic film protecting the front of the indicator.

#### Panel cut-out



#### Recommended minimum spacing of indicators



## 1.2.2 Removing The Indicator From The Sleeve

The indicator can be removed from its sleeve by easing the latching ears outwards and pulling it forward out of the sleeve. When plugging the indicator back into its sleeve, ensure that the latching ears click into place to maintain the moisture sealing protection.

It is recommended that power to the controller is turned off when removing or replacing the controller into its sleeve, to prevent premature wear on the connectors when current is flowing through them.

## 1.3 New Sleeve Design MkIII

From Jan-03 an improved design of 1/8 DIN long sleeve is shipped with all new 2408 controllers and indicators. (The month and year of manufacture are shown in the last two pairs of digits of the instrument serial number).

#### 1.3.1 Details

A new sealing gasket will be fitted onto the instrument bezel  $\mathbb{O}$ . This gasket replaces the gasket which was moulded into the front of the sleeve of all previous instruments.

The gasket previously moulded into the sleeve where it fits behind the panel is now supplied as a separate item ②.

#### 1.3.2 Reasons for the Change

This change is to ensure that IP65 sealing is reliably achieved and less physical effort is required to insert the instrument into the new sleeve.

#### 1.3.3 Recommendations

- 1. An instrument delivered after Jan 03 should be used with the sleeve supplied
- 2. If the instrument is required to replace one already in use, the existing sleeve should also be replaced
- 3. A new instrument can be fitted into an existing sleeve by carefully removing gasket  ${\mathbb O}$  but IP65 sealing will not be maintained
- 4. An existing instrument can be fitted into a new sleeve but IP65 sealing will not be maintained

It is, however, possible to achieve IP65 sealing for 3 and 4 above. A gasket kit is available from Eurotherm by quoting Part No SUB24/GAS2408.

Then:-

- 5. To fit a new instrument in an older sleeve carefully remove gasket ①. Replace it with the thinner (1.25mm) gasket from the kit
- 6. To fit an existing instrument into a new sleeve fit the thicker (1.6mm) gasket from the kit between the instrument and the sleeve

The seal ② supplied as a separate item with a new instrument, should be placed over the sleeve prior to mounting it through the panel cut out as shown below:-



Typical

## 1.4 Electrical Connections



#### 1.4.1 Wiring

The screw terminals accept wire sizes from 0.5 to 1.5 mm<sup>2</sup> (16 to 22 AWG) and should be tightened to a torque of 0.4Nm (3.5lb in). Hinged terminal covers provide IP20 protection.

#### 1.4.2 Plug-in Module Connections

Modules are fitted in positions 1, 2 and 3 in accordance with the ordering code. The tables below show the connections for each module and the possible functions they can perform.

Note: On the wiring label the module number precedes the terminal identity letter given in the table below. For example, 1A, 1B, 1C.

Module

Module Type	Terminal Identity		Typical		
	Α	В	С	D	Functions
Relay; changeover		•			Alarm or Event
Dual relay (normally open)	ſ		Le		Alarms or events
DC retransmission	+	-			Analogue retransmission of PV
Transmitter supply 24V	+	-			To power transmitters
Strain Gauge Transducer supply (see note 1)	+	-	C resi	al stor	To power strain gauges. (5V or 10V selectable)

Туре	Α	В	C	D	Functions
2nd Analogue Input			+	-	Thermocouple
(Analogue Input 2) (module 3					PRT
only)			+	-	mA (2.49Ω
[			4		sense resistor)
			+	-	High impedance 0 - 2.0Vdc
			+	-	millivolts
	+			-	0 - 10Vdc
Triple contact input	ip1	ip2	ip3	Com	
Triple digital input	ip1	ip2	ip3	Com	
Triple digital output	op1	op2	ор3		

**Terminal Identity** 

- Notes:-
- 1. By default:

The transducer supply for input 1 is installed in module position 2

The transducer supply for input 2 is installed in module position 1

- 2. All module connections are isolated from the process value, earth, incoming supply and connections to other modules.
- Digital inputs are non-isolated from the process value.
   Digital inputs are powered by the indicator. Switching voltage and current 24Vdc/20mA.



#### 1.4.3 Communications Modules

Digital Communications Module					
	Terminal identity				
Module type	HB	нс	HD	HE	HF
RS232	-	-	Com	Rx	Тx
RS485 (2-wire)	-	-	Com	A (+)	B (-)
RS485 (4-wire)	Rx+	Rx-	Com	Tx+	Tx-
Profibus	Shield	VP	В	А	DGND

PDS Module						
	Terminal identity					
	JD JE JF					
Setpoint Input	tpoint Input - Signal					

## 2 Operation

Switch on the indicator. After a 3 second self-test sequence, you will see the display shown below. This is called the '**HOME'** display.



## 2.1.1 To View The Display Units

If the indicator has been configured for a thermocouple or RTD input, the temperature units can be viewed as follows:

Do This	This Is The Display You Should See	Additional Notes
1. Press and quickly release the  or   or   button.	0.5 sec	Display Units <sup>12</sup> Celsius OR <sup>17</sup> Fahrenheit OR <sup>17</sup> Kelvin The display units are shown for 0.5 second Note: For linear inputs no units are displayed. In this case: Press <sup>12</sup> to go directly to the <b>d 5</b> P display - see section 2.1.2. Press <sup>15</sup> to go directly to the <b>f</b> L List - see section 2.2.4.

#### 2.1.2 Home Display Options

When shipped from the factory the HOME display will show the measured temperature or process value. This is the '<u>front</u>' display.

If either  $\boxed{\bullet}$  or  $\boxed{\bullet}$  is pressed the display changes to the '<u>back</u>' display for a period of two seconds. The back display can show an alternative measurement, such as alarm setpoint or second PV input value.

Do This	This Is The Display You Should See	Additional Notes			
Example	'back' display =	Parameters w	hich can be allocated to the Front and Back		
1.From the HOME display, press 🔽 or 🔺	Alarm setpoint.	<none></none>	The HOME display will be blank and only alarm messages will be flashed		
	2 secs	<5P>	Setpoint (for deviation alarms)		
		<rm.5p></rm.5p>	Remote setpoint (for deviation alarms)		
		<pu.h,></pu.h,>	Displays the maximum value on input 1		
		<pulo></pulo>	Displays the minimum value on input 1		
	or 📥	<pu></pu>	Process Value		
	frank dian law	<al.sp></al.sp>	Alarm 1 setpoint		
adjust the Alarm Setpoint	Process Value	<l 1=""></l>	Linearised input 1		
between hi & lo limits		<l2></l2>	Linearised input 2		
		Note: If the indicator has been ordered to read the higher code HI) or lowest values (order code LO) between and 2, the display shows only this value. If PV function ordered as FN, the displayed reading derived from inputs 1 and 2. The back display is not selectable in this mode			
💮 Pressing 🗋 and	🕑 together will always return to	the HOME di	isplay.		
	OR				

The display will always return to the HOME display if no button is pressed within 45 seconds. This time is reduced to 10 seconds if an alarm is being displayed.

#### 2.2 Alarms

**Alarms** are used to alert an operator when a pre-set level has been exceeded. They are normally used to switch an output (see section 2.2.2.) - usually a relay - to provide external actions to the process.

Soft Alarms are indication only and do not operate an output.

**Events** are generally defined as conditions, which occur as part of the operation of the plant. They do not require operator intervention and, therefore, do not cause an alarm message to be displayed. They can be attached to operate an output (relay) in the same way as an alarm.

#### 2.2.1 Types of Alarm Used In The 2408i

This section shows graphically the operation of different types of alarm used in the indicator. The graphs show changes in PV plotted against time. The PV may be derived from input 1, input 2 or the main PV which is derived from input 1 & 2.



**Rate of change alarms** detect if the rate of change in PV, set as units per minute or per second, exceeds the setpoint value. An alarm setpoint set + will detect positive rates of change. An alarm setpoint set - will detect negative rates of change. Therefore, if it is required to measure the rate of change in both directions then two alarms must be configured. Since rate of change alarms are calculated over a period of time a small delay may be apparent before the alarm is indicated. This is generally only noticeable if the PV changes very quickly.

**Hysteresis** is the difference between the point at which the alarm switches ON and the point at which it switches OFF.

It is used to prevent relay chatter.

Latching Alarms see 2.2.6

#### 2.2.2 Alarm Relay Output

Alarms can operate a specific relay or logic output. Any individual alarm can operate an individual output or any combination of alarms can operate an individual output. They are either supplied pre-configured in accordance with the ordering code or set up in configuration level. Deviation Alarms. The setpoint used for deviation alarms is normally derived as a remote input from another device - for example, a temperature controller. The setpoint can also be internally set within the controller - in this case called the local setpoint value.

Delay a settable time between an alarm occurring and it being displayed on the indicator

**Blocking Alarms** only occur <u>after</u> the start up phase when the alarm has first entered a safe state. The alarm is only indicated the next time it is active. It is used, for example, to ignore start up conditions which are not representative of running conditions.



Any combination of alarms can operate the relay or logic output. The diagram shows typical alarms

#### 2.2.3 Alarm Indication

An alarm occurs when the process conditions exceed a pre-set level (setpoint). It will be displayed on the indicator as follows:-

- 1. The relevant alarm beacon will begin to flash
- 2. A four character alarm message will be shown as a double repeating flash in the main display. This message specifies the alarm number (first character) and the type of alarm that has occurred (next three characters). The message is flashed in addition to the 'front' displayed value

If more than one alarm is present the relevant beacon illuminates and further messages are flashed in the main display. The alarm indication will continue while the alarm condition is present and is not acknowledged.



'The message indicates the alarm type eg. < IF5L> = Alarm <u>1 Full S</u>cale Low See 'Alarm Messages' below for the full list.

#### 2.2.4 Alarm Messages

Display	Alarm type	Input Source	Alarm description and function					
First charact	First character							
			Alarm <u>1</u> is active					
2			Alarm <u>2</u> is active					
]			Alarm <u>3</u> is active					
4			Alarm <u>4</u> is active					
Last three ch	naracters							
-FSL	<u>F</u> ull <u>S</u> cale <u>L</u> ow	Main PV	The process value is:-	below the low alarm setting on the main PV				
-FL I		PV 1		below the low alarm setting on PV 1				
-FL2		PV 2		below the low alarm setting on PV 2				
-FSH	<u>F</u> ull <u>S</u> cale <u>H</u> igh	Main PV		above the high alarm setting on the main PV				
-FH I		PV 1		above the high alarm setting on PV 1				
-FH2		PV 2		above the high alarm setting on PV 2				
-dLo	Deviation Low	Main PV		below the low deviation setting on main PV				
-dL		PV 1		below the low deviation setting on PV1				
-dL2		PV 2		below the low deviation setting on PV2				
-dH,	<u>D</u> eviation <u>Hi</u> gh	Main PV		above the high deviation setting on main PV				
- dH 1		PV 1		above the high deviation setting on PV1				
-dH2		PV 2		above the high deviation setting on PV2				
-dEu	Deviation Band	Main PV		above or below the high and low deviation setting on main PV				
-du l		PV 1		above or below the high and low deviation setting on PV1				
-du2		PV 2		above or below the high and low deviation setting on PV2				
-rAE	<u>Rat</u> e of change (minutes)	Main PV		changing faster than the rate-of change alarm setting in minutes for main input.				
-rA5	<u>Rat</u> e of change (seconds)	Main PV		changing faster than the rate-of change alarm setting in seconds for main input.				
-rt	<u>Rat</u> e of change (minutes)	Input 1		changing faster than the rate-of change alarm setting in minutes for input 1.				
-r51	<u>Rat</u> e of change (seconds)	Input 1		changing faster than the rate-of change alarm setting in seconds for input 1.				
-r£2	<u>Rat</u> e of change (minutes)	Input 2	changing faster than the rate-of change alarm setting in minutes for input 2.					
52	<u>Rat</u> e of change (seconds)	Input 2		changing faster than the rate-of change alarm setting in seconds for input 2.				
-LSP	<u>S</u> et <u>p</u> oint <u>L</u> ow	Main PV	The setpoint is:-	below the low alarm setting				
-HSP	<u>S</u> et <u>p</u> oint <u>H</u> igh	Main PV		above the high alarm setting				
5br				Sensor Break alarm (open circuit input on whichever input is being used as the PV)				



If the **process value flashes** but no other alarm message is displayed, this indicates that the input which is being used as the PV is out of range.

#### 2.2.5 Diagnostic Alarms

In addition to the process alarms given in the previous column the following diagnostic alarms may also appear.

These warn that a fault exists in either the indicator or the connected devices.

Alarm	What it means	What to do about it		
EEEr	<i>Electrically Erasable Memory Error:</i> The value of an operator or configuration parameter has been corrupted.	This fault will automatically select configuration level. Check all configuration parameters before returning to operator level. Once in operator level, check all operator parameters before resuming normal operation. If the fault persists or occurs frequently, return the unit for repair.		
LLLL	Out of range low reading	Check the value of the input		
НННН	Out of range high reading	Check the value of the input		
Err 1 Error 1: ROM self-test fail		Return the indicator for repair		
Error 2: RAM self-test fail		Return the indicator for repair		
Err3	Error 3: Watchdog fail	Return the indicator for repair		
<b>Errry</b> Error 4: Keyboard failure. Stuck button, or a button was pressed during power up.		Switch the power off and then on without touching any of the indicator buttons. If the error continues return the unit for repair.		
ErrS	Error 5: Input circuit failure	Return the unit for repair		
Hw£r	<i>Hardware error</i> Indication that a module is of the wrong type, missing faulty, or a new module has been fitted.	Check that the correct modules are fitted. Go to configuration mode and set up the required parameter(s). See section 4 for further information.		
Pwr F	Power failure: The line voltage is too low	Check that the supply is within rated limits		
rmEF	Remote input fail	Connect an input device (eg. transducer, thermocouple, mA source) to input 2		

#### 2.2.6 To Acknowledge An Alarm

An alarm can be acknowledged in two ways:-

- 1. Press the ACK/RESET button. (If this does not work it may have been disabled when the indicator was configured).
- 2. Press 🕑 and 🕒 together.

The action, which now takes place, will depend on the type of latching, which has been configured

#### Non Latched Alarms

If the indicator has been configured for non-latching alarms the following action occurs:-

**Alarm condition present when the alarm is acknowledged**, will be indicated by a single repeating flash of the alarm message and the beacon will continuously illuminate. This state will continue for as long as the alarm condition remains. When the alarm condition disappears the indication will also disappear.

If a relay has been attached to the alarm output, it will operate when the alarm condition occurs and remain in the operated condition until the alarm is acknowledged **AND** it is no longer present.

If the alarm condition disappears before it is acknowledged the alarm indication disappears as soon as the condition disappears.

#### Latched Alarms

The indicator may have been configured for Automatic or Manual reset. The action which occurs when the acknowledge button is pressed is described below:-

#### Automatic.

The alarm continues to be active until both the alarm condition is removed AND the alarm is acknowledged. The acknowledgement can occur **BEFORE** the alarm condition is removed.

#### Manual

The alarm continues to be active until both the alarm condition is removed AND the alarm is acknowledged. The acknowledgement <u>can only occur</u> **AFTER** the alarm condition is removed.

#### 2.2.7 Alarm Inhibit

If a digital input has been configured for alarm inhibit, then all process alarm indication will be prevented for as long as the input is ON. When the input is turned to OFF any alarms which are active will be displayed. If a delay has been set on the alarm, the delay period will start from the time when the input is turned OFF. If the alarm has been configured as latching the latching action is also inhibited whenever the input is ON. See section 4.5.4 and 4.5.6.

#### 2.2.8 To Change The Alarm Setpoints (trip levels)

Parameters are grouped in 'lists' according to their function. Each list has a heading.

The 🕒 button steps through the parameter list headings (see section 2.4.1.)

The first list is the alarm setpoints list  $\mathcal{RL}$ 

Do This	This Is The Display You Should See	Additional Notes
1. From any display press 🕒 as many times as necessary to show the <b>'Alarm List'</b> header	FL	If or are pressed the word <l, 5l=""> is displayed for 2 secs</l,>
<ol> <li>Press to show the first parameter in the list</li> <li>Press or to change the alarm setpoint</li> </ol>		<ul> <li>There are four alarm setpoints. The first character is the alarm number, the next three the alarm type (see section 2.2.4.)</li> <li>If an alarm has been disabled in configuration level, it will not appear in this list.</li> </ul>
4. To return to the HOME display:-		

• Press 🕝 and 🗈 together

• or continue to press

\_. . **.** 

• or the indicator will return to the HOME display if no button is pressed for 45 seconds (10 seconds if an alarm condition is present).

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## 2.3 Auto-Tare (Display Zero)

The auto-tare function is used, for example, when it is required to weigh the contents of a container but not the container itself. Alternatively, it can be used to set a fixed offset on an initial measured value.

## 2.3.1 To Use Auto Tare

Place the empty container on the weigh-bridge. Then:-

Do This		This Is The Display You Should See	Additio	onal Notes
1.	From any display press as many times as necessary to show the < <b>[</b> <i>AL</i> <b>1&gt; List'</b> header	EAL 1		Use <b>&lt;[AL2</b> > if the load cell is connected to input 2
2.	Press to scroll to <b><eare< b="">&gt;</eare<></b>			The indicator automatically calibrates itself to the empty container.
3.	Press or or and change from <off> to &lt;חם&gt;</off>	EARE on		When <b>&lt;</b> EArE> is turned to <b>&lt;an</b> >, the display will change to <b>&lt;buSY</b> >. When calibration is complete the display will return to the HOME display.
				It will then return to the main display.
				If the calibration fails the alarm message $< \mathbf{Edr} F > (\underline{transducer fail})$ will flash. Press and $\bigcirc$ to acknowledge.
				bu5Y→ 20

#### 4. Return to the HOME display as described above

#### Note:-

The indicator will not return to the HOME display until the calibration procedure completes.

If calibration does not complete after a period of 5 minutes, then calibration is aborted.

Goto

G

## 2.4 To Access and Change Parameter Values

Parameters are settings within the indicator, which determine how it will operate. Examples are Alarm Setpoints and Tare Values already mentioned. They are organised into different lists. Each list has a named heading which describes a particular subject, for example 'Alarms'  $\langle RL \rangle$ 

## 2.4.1 Operator Level Navigation Diagram (factory default)

This list shows the parameters available in operator level in a new instrument.

SP H

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To find a parameter:-



G

• Blocks shown shaded are dependant upon the order code as follows:-

(1)

(1)

(1)

2-

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4--

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dSP.Ь

C, d

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(1) These parameters are only shown if the alarm has been configured

(2) CAL2 list is only shown if Input 2 has been configured

• The above list can be customised to suit the requirements of a particular process. Complete lists or individual parameters in a list can be added during commissioning. The procedure is described in section 3.4 'To Hide. Reveal and Promote Parameters'.

Only present if ordered with

configuration options SG or MP, see ordering code section 5. See also section 3 for the full list of

parameters available and calibration details.

#### 2.5 Parameter tables

The parameter tables provide a full list of parameters, an explanation of their use and where to find them.

Use these lists to adjust:-

- The alarm setpoints
- The User calibration
- The communications address

- The alarm setpoint limits
- The input filter time constant

## 2.5.1 HOME List



HOME	Home List	Selectable op	tions	Default
d5P,F	HOME <u>disp</u> lay <u>f</u> ront	<none></none>	The HOME display will be blank and only alarm messages will be flashed	РU
		<5P>	Setpoint (for deviation alarms)	
		<rm.5p></rm.5p>	Remote setpoint (for deviation alarms)	
		<puh,></puh,>	Displays the maximum value on input 1. This parameter is the same as <lodh> in &lt;1 nFo&gt; list</lodh>	
		<pulo></pulo>	Displays the minimum value on input 1. This parameter is the same as <lodl> in &lt;1 nFo&gt; list</lodl>	
		<pu></pu>	Process Value	
		<r< th=""><th>Alarm 1 setpoint</th><th></th></r<>	Alarm 1 setpoint	
		<l 1=""></l>	Linearised input 1	
dSP.b	HOME <u>disp</u> lay <u>b</u> ack	<l2></l2>	Linearised input 2	
E' q	<u>C</u> ustomer defined <u>id</u> entity number - an indicator can be associated with a physical position	0 to 9999		٥

## 2.5.2 Alarm List



AL	<u>Al</u> arm list	Comments	Adjustable Range	Default
	Alarm <u>1</u> setpoint	The last three letters indicate the	Between low and high setpoint limits which	۵
2	Alarm <u>2</u> setpoint	Alarm type. See section 2.2.4.	As set in the <b>5P</b> list.	0
]	Alarm <u>3</u> setpoint	If the alarm is disabled the parameter	Rate of change alarms are direction sensitive	۵
4	Alarm <u>4</u> setpoint	will not appear in this list	from-9999 to +99999 units/sec or min	0

## 2.5.3 Setpoint List



SP	<u>S</u> et <u>p</u> oint list	Adjustable Range	Default
SP L	<u>S</u> et <u>p</u> oint <u>l</u> ow limit - PV alarms	Input range min and max (combination of	As per
SP H	<u>S</u> et <u>p</u> oint <u>h</u> igh limit - PV alarms	inputs 1 & 2	Order code

#### 2.5.4 Input List

۰P			
- • ↓			
ı P	<u>S</u> et <u>p</u> oint list	Adjustable Range	Default
, nEE	Input filter integrating time constant	OFF to 999.9 seconds	1.6
	Set to a value which reduces the effect of any input noise to an acceptable level. The higher the value the more sluggish the response		

#### 2.5.5 User Calibration Lists - Inputs 1 and 2

€ ↓			
EAL	User calibration 1 or 2 list	Adjustable Range	Default
Full	Performs automatic ' <u>Tar</u> e' correction	<b>DFF</b> = Off	OFF
	See also section 2.3.	= start correction <b>bu54</b> = inputting value	
		donE = finished inputting value	

(CAL 2 only appears if input 2 has been configured)

#### 2.5.6 Access List

EAL. I

or

EAL.2

The Access List provides password protected access to further levels of operation as listed below. AEES See section 3 for further details. € ↓ codE A code number can be entered using the 🔽 or 🔺 buttons. If an incorrect code number is entered the display will revert to <code >. If no button is pressed within 45 seconds the indicator will automatically return to the HOME display.

For information on further levels of access, see the following sections.

## 3 Password Protected Levels of Operation

## 3.1 Access levels

Parameters are protected under different levels of access for which numerical password codes can be set up. The levels are:-

Access Level	What you can do	Default Code
DPEr	To view and adjust a limited set of parameters within limits set in higher levels	
Full	To view and adjust all parameters which are required to operate the indicator	1
Edi E	Allows parameters to be hidden or promoted to operator levels (see section 3.4)	1
EonF	Allows access to configure the fundamental characteristics of the indicator	2
CAL.P	This special level which appears in the CAL1 and CAL2 lists allows access to the calibration procedure for the indicator	Э

The following sections this manual describe the features available in Full, Edit and Configuration levels.

## 3.1.1 To Select Full or Edit Access Levels

Do This	This Is The Display You Should See	Additional Notes
1. From any display press as many times as necessary to access the <b>'Access List'</b> header menu	ACCS	If or are pressed the word <l, se=""> is displayed for 2 seconds</l,>
<ol> <li>Press  to show <code> Press  or  to enter the password</code></li> <li>Press  to show &lt;<b>CoLo</b>&gt;</li> </ol>	2 secs PASS codE	The factory default password is 1 <pa55> will be displayed momentarily when the correct password is been entered In the special case that the passcodes have been configured as D, it will not be necessary to enter a passcode</pa55>
<ol> <li>Press ▼ or ▲ to select <full> level</full></li> </ol>	2 secs <b>Full</b> <b>Goto</b>	Options are: <dper> Operator level - shows selected operator parameters <full> Reveals the 'FULL' set of parameters <ed, l=""> Allows parameters to be hidden or promoted <conf> Gives access to configuration level (see section 4). The factory default password is 2</conf></ed,></full></dper>

Having entered a higher level you can select  $\langle DPE_{r} \rangle$ ,  $\langle Full \rangle$  or  $\langle Ed_{r} \rangle$  levels at will.

Remember to return to  $\langle DPEr \rangle$  level following completion of commissioning or configuring the instrument.

This may be done by:-

1. Switching the indicator off and back on again.

OR

 $\odot$ 

2. Go to  $< \square PE_{r} >$  level and enter a false password number to re-lock the indicator in this level.

## 3.2 Navigation Diagram (full and edit levels)

Use the following lists to adjust:

- The alarm setpoints
- The alarm setpoint limits
- The input filter time constant
- The User calibration
- The communications address

The diagram below shows the complete list of possible parameters which may be shown in Full and Edit access levels. In practice, the parameters that appear will depend upon the configuration of your particular indicator .



Figure 3-1: Navigation Diagram

#### Summary

- A. Press 🕒 to step across the list headings.
- B. Press 🕝 to step down the parameters within a particular list. You will eventually return to the list heading.
- C. Press 🚺 to view the value of a selected parameter. Keep pressing to decrease the value.
- D. Press 🔺 to view the value of a selected parameter. Keep pressing to increase the value.



 Only shown if:- <mUI>, <UI> or <m用I> are configured, see Sensor Input Configuration List section 4.5.2.

## 3.3 Parameter Tables

## 3.3.1 HOME List

20 ↓

Mnem -onic	Meaning	Adjustable Range	Default setting	Customer setting
dSPF	HOME <u>disp</u> lay <u>f</u> ront	See 'HOME display options'	PU	
dSP.Ь	HOME <u>disp</u> lay <u>b</u> ack	section 2.1.2.	None	
E, d	<u>C</u> ustomer defined <u>id</u> entity number	0 to 9999	٥	

#### 3.3.2 Alarm List

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*					
Mnem	Meaning		Adjustable Range	Default	Customer
-onic				setting	setting
1	Alarm <u>1</u> setpoint	In place of dashes, the	Between low and high setpoint	0	
2	Alarm <u>2</u> setpoint	last three letters	limits which are set in the	0	
3	Alarm <u>3</u> setpoint	as shown in the <b>'Alarm</b>	<5P> list	0	
4	Alarm <u>4</u> setpoint	Messages' table section 2.2.4.	Rate of change alarms are direction sensitive from-9999 to +99999 units/sec or min	0	
If the a	larm is disabled the p	barameter will not appea	r in this list		•
HY I	Alarm 1 <u>Hy</u> steresis	Prevents relay 'chatter'	1 to 99999 display units	1	
HY 2	Alarm 2 <u>Hy</u> steresis	by setting a difference	1 to 99999 display units	1	
НЧ Э	Alarm 3 <u>Hy</u> steresis	between the relay ON	1 to 99999 display units	1	
HY Y	Alarm 4 <u>Hy</u> steresis		1 to 99999 display units	1	
IdEL	Alarm <u>1 del</u> ay	Used to ignore	🛿 to 999.9 seconds	0	
29E7	Alarm <u>2</u> <u>del</u> ay	transient alarms.	1 to 999.9 seconds	0	
39EF	Alarm <u>3 del</u> ay	the delay time before	🛿 to 999.9 seconds	0	
HAEL	Alarm <u>3 del</u> ay	they become active	1 to 999.9 seconds	0	
InAL	Inhibit alarm timer	To inhibit alarms for a	On/OFF	OFF	
InHE	Time alarm inhibited	time, see section 4.5.5	1 to 999.9 seconds	0	

## 3.3.3 Setpoint List

5P

ۍ ا Mnem Adjustable Range Default Customer Meaning -onic setting setting L- r Loc Select local SP Loc Remote setpoint enable гmЕ Select remote SP rm.5P N/A Remote master setpoint (for deviation alarms) Displays remote SP value Read only OFF DFF rm.Er Remote setpoint track. No tracking ErAc Local SP tracks This parameter only appears if remote setpoint has been configured remote SP SP SP IL to SP IH 20 1 Local master setpoint value for deviation alarms on input 1 5P 2 SP2L to SPH2 Local master setpoint value for deviation 20 alarms on input 2 SP SPL to SPH Setpoint value when the combination of inputs 1 & 2 provide the measured value to the indicator (for deviation alarms) SP L SP H PV Alarms <u>Setpoint low limit</u> Input range min and max As per order code (combination of input 1 2) <u>Setpoint High limit</u> SP IL SP IH Input <u>1</u> Alarms <u>S</u>etpoint <u>L</u>ow Between input 1 sensor range As per order min and max code <u>S</u>etpoint <u>H</u>igh SP2L Input <u>2</u> Alarms <u>Setpoint Low</u> Between input 2 sensor range As per order SP2H min and max code <u>Setpoint High</u>

Γ

3.3.4 Input List

۰P							
Ð							
♦ Mnem- onic	Meaning			Adjustab	le Range	Default setting	Customer setting
F, LE	Input 1 <u>Filt</u> er Type	For explanation see section 3.	on of filter action 3.4.2.	OFF Int Step	No input filter Integrating <u>Step</u>		
l n££	Input 1 <u>filt</u> er time constant	Appears if Filt <i nl=""> Used process value input other the</i>	er Type = to reduce flicker on any an weigh scales	OFF to	999.9 seconds	1.5	
SEP.b	Input 1 filter Step <u>B</u> and	Appears if Filt < <b>5LEP</b> > Use process value scale inputs	er Type = ed to reduce flicker on weigh	1 to 10 (% maxim	0 num noise band)	10	
The above	three parameters are	repeated for inp	out 2 as <fle2>, ·</fle2>	<1. n2.E> a	and <522.6> respe	ctively	
OFS I	Input 1 calibration <u>Offs</u> et	See section 3.	5.1	<b>999.9</b> to	999.9		
OF52 (1)	Input 2 calibration <u>Of</u> f <u>s</u> et			<b>999.9</b> to	999.9		
E J P H, J P F. 1 <sup>(2)</sup> F2 <sup>(2)</sup> PU, P <sup>(1)</sup>	Transition of indication between input 1 and 2 (if configured) • The displayed value is derived from input 1 when PV is below $$ and from input 2 when PV is above $$ • When PV is between $$ and $$ the displayed value is a combination of both inputs • $$ cannot be set to a value above <hijp> This is described further in section 4.6.9.1 <f. i=""> and <math><f.2></f.2></math> are constants to achieve a derived PV where PV = <math><f. i=""></f.></math> x input 1 + <math><f.2></f.2></math> x input 2 Selects input 1 or input 2</f.></hijp>		-9.99 to 10.00 -9.99 to 10.00 -9.99 to 10.00 -9.99 to 10.00 -9.99 to 10.00		As per order code		
				, P.2	Input 2 selected		
	Input <u>1 mV</u> measure	d at the rear te	rminals			Read-only	Read-only
	Input <u>2 mV</u> measure	d at the rear te	rminals (module 3)			Read-only	Read-only
	Input <u>1</u> Cold junction compensation temperature measured at the rear termin Only applies if the input 1 type = thermocouple			e rear terminals.	Read-only	Read-only	
	Input <u>2</u> <u>C</u> old junction (module 3) Only app	n <u>c</u> ompensation plies if the input	n temperature mea t 2 type = thermoco	sured at the ouple	e rear terminals	Read-only	Read-only
Emi 5	Input <u>1 Emis</u> sivity. Only applies if the input 1 type = pyrometer						
Em5.2 <sup>(1)</sup>	Input <u>2 Emis</u> sivity. Only applies if the input 2 type = pyrometer						
Li.l	Input <u>1</u> Linearised va	alue				Read-only	Read-only
	Input <u>2</u> Linearised va	lue (module 3)				Read-only	Read-only
PU.SL	Shows the currently selected PV input	, P.1 , P.2 60Eh	Input 1 selected Input 2 selected Both input 1 and	input 2 are	configured	, P. I	

#### Notes:

- (1) These parameters only appear if input 2 has been configured
- (2) These parameters only appear if a derived input has been configured

## 3.3.4.1 Example: To Measure to Differential Between Input 1 and Input 2

- From the above list, select  $\langle F. I \rangle$  and set its value to 1. 1.
- From the above list, select  $\langle F 2 \rangle$  and set its value to -1. 2.
- The derived PV will read the difference between Input 1 and Input 2 3.

## 3.3.4.2 Filter Type

There are three settings for the filter type

- 1. Filter Type = Off. The display will respond immediately to any change in the PV input. If, however, there is any input noise this will result in fluctuations of the reading
- 2. Filter Type = Integrating action. This is designed for all process input types with the exception of weigh cell transducers as explained in section 3.6. The function is exponential which means that, for a step change in the input, the displayed value will move rapidly at first towards the new reading then gradually slow as the reading approaches the PV value. The effect is that small rapidly changing input values are ignored. The rate of response is set, in seconds, by the parameter I nEL, which only appears for this type of filter. The larger the value the more sluggish the response
- 3. Filter Type = Step Band. This is specifically designed for weighing applications. The filter only responds when the displayed value becomes close to the measured value. This means that for a step change in the input the displayed value will change rapidly towards the measured value then slow as it reaches this value. The step band is set by the parameter 5LP.b which only appears for this type of filter. The units approximate to 1μV steps the larger the setting more sluggish the response over the final stages of the reading. This type of filter is used, for example, where a weigh bridge or load cell is subject to vibrations

## 3.3.5 User Calibration Lists

These lists only appear if the 'Type of Calibration',  $\langle EYPE \rangle$ , is configured for strain gauge type transducer applications (see Configuration Chapter for further details). The lists below are shown for each type of calibration. If  $\langle EYPE \rangle = \langle IFF \rangle$  the lists are not displayed.

Some parameter mnemonics remain the same for each type of transducer, but their functions may vary in detail between the different types. The tables are repeated, therefore, for each calibration type.

The tables are followed by a description of procedure to use for each type of calibration.

#### 3.3.5.1 Calibration Type = Shunt (<EYPE> = <5hnE>)

See also section 3.6.1.



<b>.</b>	<u> </u>							
Mnem- onic	Meaning		Adjustak	ble Range	Default setting	Customer setting		
EArE	Performs auto	matic ' <u>Tar</u> e' correction	<b>DFF</b> = Off		DFF			
	See 'USER CA	LIBRATION' section for	on =	= Start correction				
	further description		6и5У =	Calculating value				
EAL P	<u>Cal</u> ibration <u>p</u> a CALIBRATION	assword -See 'USER I'	0 to 99	999	Ξ			
The follow	ing three param	eters only appear when the corre	ect passwo	ord has been entered				
EAL	Calibration ty	pe	FAct	<u>Fact</u> ory calibration restored	FAct			
			USEr	<u>User</u> calibration enabled				
The follow	ving two parame	eters are only shown if <b><user< b=""> &gt;</user<></b>	> is selecte	ed as the calibration type		•		
PntL	Start point <u>l</u> ov	v calibration	OFF	Calibration complete	OFF			
	Note: In shun both zero and mnemonic is applications	t mode this parameter starts I span calibration. Its common to other transducer	חם	Start calibration				
£ArE.u	<u>Tare V</u> alue	This allows a fixed offset to be applied to the displayed reading. It must be set before auto tare is started	-999.9 to 99999 display units		0.0			
5.6	<u>S</u> pecific g <u>rav</u> ity multiplier	For materials with specific gravity different from water (1)	00 l to 999.9		1.00			
ScLL	<u>Scal</u> e <u>L</u> ow poin <u>t</u>	Defines the low calibration point for the transducer (normally 0% of the transducer range)	-999.9 to 99999 display units		0			
ScL H	<u>Sc</u> a <u>l</u> e <u>H</u> igh poin <u>t</u>	Defines the high calibration point for the transducer (normally 80% of the transducer range)	-999.9 t	to <b>99999</b> display units	0			

## 3.3.5.2 Calibration Type = Load Cell ( $< t \forall PE > = < LdE >$ )

See also se	ction 3.6.3.
EAL I	CAL2
U	C

•		*				
Mnem- onic	Meaning		Adjusta	ble Range	Default setting	Customer setting
EArE	Performs au	tomatic ' <u>Tar</u> e' correction	OFF	= Off	OFF	
	See 'User Calibration' section for further		п	= Start correction		
	description		ЬобУ	= Calculating value		
EAL.P	Calibration	<u>p</u> assword -See 'USER DN'	0 to 9	3999	3	
The follow	ing four para	meters only appear when the corre	ect passw	ord has been entered		
EAL	Calibration	type	FAct	<u>Fact</u> ory calibration restored	FAct	
			USEr	User calibration enabled		
The follow	illowing three parameters are only shown if $< \square SEr >$ is selected as the calibration type					
PntL	Start point low calibration OFF Calibration complete		Calibration complete	DFF		
			ол	Start low point calibration		
PntH	Start point <u>h</u>	igh calibration	OFF	Calibration complete	OFF	
			חם	Start high point calibration		
EArE.u	<u>Tare</u> <u>V</u> alue	This allows a fixed offset to be applied to the displayed reading. It must be set before auto tare is started	-999.9	to 99999 display units	00	
50	<u>S</u> pecific <u>gr</u> a <u>v</u> ity multiplier	For materials with specific gravity different from water (1)	0.0 l to 999.9		1.00	
ScL.L	<u>Scal</u> e <u>L</u> ow poin <u>t</u>	Defines the value which will be displayed when the load is removed from the cell	-999.9	to <b>99999</b> display units	0	
Scl.H	<u>Scal</u> e <u>H</u> igh poin <u>t</u>	Defines the value which will be displayed when the load is placed on the cell	-999.9	to <b>99999</b> display units	0	

## 3.3.5.3 Calibration Type = Comparison < P = < mP >

See also section 3.6.5.

¥	¥					
Mnem- onic	Meaning		Adjust	able Range	Default setting	Customer setting
EArE	Performs auto	omatic ' <u>Tare</u> ' correction.	DFF	= Off	DFF	
	See 'USER CA	LIBRATION' section for further	оп	= Start correction		
	description		ЬобУ	= Calculating value		
EALP	Calibration pa	assword.	0 to 9	9999	Ξ	
	See 'USER CA	LIBRATION'				
The follow	ving four param	eters only appear when the corre	ect passw	ord has been entered		
EAL	Calibration ty	ре	FAct	Factory calibration	FAct	
				restored		
			USEr	<u>User</u> calibration enabled		
The follow	ving three parar	neters are only shown if <b><user< b="">&gt;</user<></b>	> is select	ted as the calibration type		
PntL	Start point <u>l</u> ov	v calibration	OFF	Calibration complete	DFF	
			п	Start low point calibration		
PntH	Start point <u>h</u> ig	h calibration	OFF	Calibration complete	OFF	
			п	Start high point		
				calibration		
EArE.u	<u>Tare</u> <u>V</u> alue	This allows a fixed offset to	-999.9	to <b>99999</b> display units	0.0	
		reading It must be set				
		before auto tare is started				
5.0	<u>S</u> pecific	For materials with specific	<b>0.0 1</b> t	o <b>999.9</b>	1.00	
	<u>gr</u> a <u>v</u> ity	gravity different from water				
	multiplier	(1)				
Sell	<u>Scale</u> <u>L</u> ow	Automatically adjusts to the	-999.9	to <b>44449</b> display units		
	poin <u>t</u>	value entered at < <b>YnEL</b> >				
Sel H	<u>Scale H</u> igh	Automatically adjusts to the	-999.9	to <b>99999</b> display units to		
	poin <u>t</u>	value entered at <b><pnlh< b="">&gt;</pnlh<></b>				

## Calibration Type = Manual <EYPE> = <mAn>

See also section 3.6.7.

CALI or CAL2

Mnem- onic	Meaning		Adjusta	ble Range	Default setting	Customer setting
EAL P	<u>Cal</u> ibration <u>p</u> a CALIBRATION	ssword -See 'USER I'	0 to 99	1999	3	
The follow	ng four paramet	ters only appear when the correct	password	has been entered		
EAL	<u>Cal</u> ibration type		FAct USEr	Factory calibration restored <u>User</u> calibration enabled	FAct	
The follow	The following three parameters are only shown if $\langle USEr \rangle$ is selected as the calibration type					
' nPL	<u>Inp</u> ut <u>l</u> ow	Set to the low electrical input which is to correspond to the low display reading	-999.9	to <b>99999</b> display units		
Sell	<u>Sc</u> a <u>l</u> e <u>L</u> ow poin <u>t</u>	Set to the display reading corresponding to	-999.9	to <b>99999</b> display units	0	
, <sub>n</sub> PH	<u>Inp</u> ut <u>h</u> igh	Set to the high electrical input which is to correspond to the high display reading	-999.9	to <b>99999</b> display units		
SclH	<u>Scal</u> e <u>H</u> igh poin <u>t</u>	Set to the display reading which corresponds to <r nph=""></r>	-999.9	to 99999 display units	0	

#### 3.3.6 Custom Linearisation List 1 or 2



•	*			
Mnem- onic	Meaning	Adjustable Range	Default setting	Customer setting
in L	Adjust <u>l</u> ow <u>in</u> put value		min input	
UALL	Adjust displayed <u>val</u> ue corresponding to input <u>l</u> ow		min display	
ın H	Adjust <u>h</u> igh <u>in</u> put value		Max input	
UAL H	Adjust displayed <u>val</u> ue corresponding to input <u>high</u>		max display	
, n 2	Adjust <u>in</u> put break point <u>2</u> value			
UAL.2	Adjust displayed <u>val</u> ue corresponding to point <u>2</u>			
to		The <u>val</u> ues entered must be continuously increasing or decreasing		
ın 14	Adjust <u>in</u> put break point <u>14</u> value			
UAL. 14	Adjust displayed <u>val</u> ue corresponding to point <u>14</u>			

This list only appears if a custom download input has been configured.

Further information on Custom Linearisation is given in section 3.7.



Having entered the values for the custom linearisation it is necessary to power down the instrument and power back up again to enter the values otherwise they will be clamped to zero. Alternatively enter then leave configuration level.

#### **Digital Communications List** 3.3.7

ᇑ				
ی ا				
Mnem- onic	Meaning	Adjustable Range	Default setting	Customer setting
Addr	Indicator communications address	l to 99 El Bisynch l to 254 Modbus	1	

This list only appears if digital communications has been configured.

## 3.3.8 Information List

ı nFo						
<u>ی</u>						
Mnem- onic	Meaning		Adjustable F	Range	Default setting	Customer setting
LoGL	Logged Minimum Process Value		Can be man	ually adjusted	Read-only	Read-only
∟⊡БН	Logged Maximum Process Value	These values are logged by the indicator	Can be man	ually adjusted	Read-only	Read-only
LoGA	Logged Average Process Value	from switch on			Read-only	Read-only
Loû£	Time process value is above threshold level	To reset switch the indicator supply off and	Time display	ved in minutes	Read-only	Read-only
Lού.υ	Process value threshold for timer log	on again or scroll to <resl> and select <yes></yes></resl>	Between dis	play min and max	0	
rESL	Logging reset		no YES	Logging in progress Will reset logged values	םח	

## 3.3.9 Access List

The Access List is the same as section 2.5.6.

AEES	
<u>ی</u> ۲	
Mnem- onic	Meaning
OPEr	To view and adjust a limited set of parameters within limits set in higher levels
Full	To view and adjust all parameters which are required to operate the indicator
Ed, E	Allows parameters to be hidden or promoted to operator levels (see section 3.4.)
EonF	Allows access to configure the fundamental characteristics of the indicator
CAL P	This special level which appears in the CAL1 and CAL2 lists allows access to the calibration procedure for the indicator

### 3.4 To Hide, Reveal and Promote Parameters

In Edit level you can choose customise the operator level display by choosing which parameters can be made available. The choices are:-

<aler></aler>	The pa	rameter	will	be	alterable
---------------	--------	---------	------	----	-----------

<H, dE> The parameter will be hidden

<rEAd> The parameter will be read-only

-Pro> The parameter will be 'promoted' into the HOME list (see below)

#### 3.4.1 List Headers

Any list of parameters shown in the Navigation Diagram, section 3.2. can be made available or hidden in Operator level.

	Do This	This Is The Display You Should See	Additional Notes
1.E	inter < <b>Ed, E</b> > level as described in 3.1.1.	<sup>2 secs</sup> Frank Goto	
2.	Press 🕒 to select the list to be hidden eg < <b>5P</b> > the setpoint parameters	² secs ✓ H. dE SP	If <b><h, b="" de<="">&gt; is selected the complete list will not be available in Operator level</h,></b>
3.	Press ▼ or ▲ to select <h, de=""> or <read></read></h,>		

#### 3.4.2 Parameters

Any parameter in a list can be made available or hidden in the same way as the complete list header as described above. They can also be made read only or promoted as shown in the two following examples.

## 3.4.2.1 The <Pro> (Promote) Option

Up to twelve commonly used parameters can be 'promoted' into the HOME list. This will give the operator quick access to them by simply pressing the button. This feature, used in combination with 'hide' and 'read only' allows you to organise the way in which you want your indicator formatted.



The parameter < IF5L> will now appear in the HOME list. Repeat the procedure for any other parameters you wish to promote.

To de-promote a parameter go to  $\langle Ed_i \rangle$  level, select the parameter from the relevant list and change the choice from  $\langle Pra \rangle$  back to  $\langle ALEr \rangle$ ,  $\langle rEAd \rangle$  or  $\langle H_i \rangle$ .

#### 3.4.2.2 Read Only Example



In this example Full scale  $\underline{H}$ igh alarm  $\underline{2}$  will be read only. This means that its value will be displayed in operator level but it cannot be changed.

## 3.5 Calibration

The indicator is calibrated in three ways. These are:-

- 1. **Factory Calibration.** The controller is calibrated to very high accuracy during manufacture and the calibration values are permanently stored within the controller. Factory calibration is not available to the user
- 2. **Transducer Scaling.** Transducer scaling allows offsets to be entered to compensate for errors or differences in the process measurement system
- 3. User Calibration. This allows the instrument to be calibrated against known conditions in the actual process without affecting the factory calibration.

See also section 3.3.5. for the full list of calibration parameters

#### 3.5.1 User Calibration

User calibration allows you to:-

- 1. Calibrate the controller to the your reference standards
- 2. Match the calibration of the controller to that of a particular transducer or sensor input
- 3. Calibrate the controller to suit the characteristics of a particular installation

The following can be calibrated:

- 1. Input 1. This applies to the fixed PV input on terminals V1, V+, V-. It allows you to set the displayed reading to correspond to the electrical input range on linear mV volt or mA inputs
- 2. **Input 2.** This applies to module 3 when fitted with a DC Input module. It allows you to set the displayed reading to correspond to the electrical input range on linear mV volt or mA inputs
- 3. Analogue I/O Modules configured as DC Retransmission. It allows you set up the electrical output to correspond with the displayed value

#### 3.5.1.1 Single Point Offset

A single offset applies to Inputs 1 & 2 and applies a fixed offset over the full display range of the controller.



To calibrate, proceed as follows:

- 1. Connect the input of the controller to the source device to which you wish to calibrate.
- 2. Set the source to the desired calibration value.
- 3. The controller will display the current measurement of the value.
- 4. If the displayed value is correct, then the controller is correctly calibrated and no further action is necessary. If it is incorrect, then follow the steps shown below.



3.5.1.2 To Apply an Offset to Input 1



#### 3.5.1.3 Two Point Calibration

Two point calibration is only available in Configuration level and allows you to adjust both the low point (zero) and high point (span) independently. The procedure is shown in the example in section 3.6.7.

## 3.6 Transducer Calibration

This indicator supports a number of different two and four wire transducer types. Each type is explained in this section.

## 3.6.1 Shunt Calibration

Shunt calibration is so called since it refers to switching a calibration resistor across one arm of the four wire measurement bridge in a strain gauge transducer. It also requires the use of a Transducer Power Supply module wired as shown in Figure 3-3.



Wiring for Transducer with Internal Calibration Resistor

Wiring for Transducer with External Calibration Resistor

Both diagrams show connections to Input 1/main input. If Input 2 is used in module position 3, the transducer output can be connected to terminals 3C (+) and 3D (-)

#### Figure 3-3: Wiring for Strain Gauge Calibration

## 3.6.2 To Calibrate a Strain Gauge Bridge Transducer

The strain gauge transducer is calibrated as follows:-

- 1. Remove any load from the transducer to establish a zero reference
- 2. Enter 'Scale Low' <ScLL> and 'Scale High' <ScLH> values which are normally set at 0% and 80% of the span of the transducer
- 3. Start the procedure using the low point calibration parameter **PnLL** >, or a digital input wired to this parameter

The indicator will automatically perform the following sequence for a transducer with its own integrated calibration resistor:

- 1. Disconnect the shunt resistor
- 2. Calculate the low point calibration value by continuously averaging two lots of 50 measurements of the input until stable readings are obtained
- 3. Connect the shunt resistor by closing a contact between terminals D and C.
- 4. Calculate the high point calibration value by averaging two lots of 50 measurements of the input

For transducers which do not contain a calibration resistor the indicator will switch in its own internal calibration resistor.

#### First - Enter The Calibration Password

Do This		This Is The Display You Should See	Additional Notes
1.	From any display press b as many times as necessary to access the <[AL 1> (or <2>) List' header	EAL I	
2.	Press 🕝 to scroll to < <b>[ALP</b> >	CAL P	
3.	Press or to enter the calibration password. In a new instrument the default is <3>	Ε	The first parameter in the list is <b><ea< b="">FE&gt; Calibration of Tare weight has already been described in Operator Level Section 2.3</ea<></b>
4.	Press to show <	✓ USEr	When the correct password is entered < <b>PR55</b> > will flash briefly on the display A password of < <b>D</b> > allows the instrument
5.	Press or to turn calibration to <user></user>		to proceed directly to the next parameter See start of this section for a description of User and Factory calibration

## Next - Calibrate the Strain Gauge Transducer

Do This	This Is The Display You Should See	Additional Notes		
<ul> <li>6. Press  to scroll to &lt;5cLL&gt;</li> <li>7. Press  or  to enter the scale low value (normally 0)</li> </ul>	ScL.L	This sets the minimum (zero) point at which the transducer is to be calibrated. This is typically 0%.		
<ol> <li>8. Press  to scroll to &lt;5cLH&gt;</li> <li>9. Press  or  to enter the scale high value</li> </ol>	5cl.H 80.00	This sets the maximum (span) point at which the transducer is to be calibrated. This is typically 80% of the transducer range.		
<ul> <li>10. Press  to show &lt; PnŁ⊥&gt;</li> <li>11. Press  or  to turn calibration to &lt; on&gt;</li> </ul>	n Pnti J	Lusy       The indicator will show 'busy' while calibrating before returning to <pnll>         If the calibration fails the alarm message <ldrf> is flashed         The <pnll> parameter may have been wired to a digital input for activation by an external switch         The operation is identical except that the indication will return to the display which was being shown prior to the activation of the switch</pnll></ldrf></pnll>		

## 3.6.3 Load Cell Calibration

A load cell with V, mV or mA output may be connected to Input 1 or Input 2.



This diagram shows connections to input 1/main input

If Input 2 is used in module position 3, the transducer output can be connected to terminals 3C(+) and 3D(-)

## 3.6.4 To Calibrate a Load Cell

The load cell is calibrated as follows:

- 1. Set <5cLL> and <5cLH> for the required 'zero' and 'span' readings on the display
- 2. Remove any load and start the procedure using the low point calibration parameter <PnL>
- 3. or a digital input wired to this parameter. The indicator will calculate the low calibration point
- 4. Place a reference weight on the load cell and turn on the high point calibration parameter <**PnL**H>, or a digital input wired to this parameter. The indicator will then calculate the high calibration point.

#### Note:-

If <PnLL'= 'On', <PnLH> cannot be turned to on

If < PnEH' = 'On', < PnEL > cannot be turned to < n >

Either must complete before the other can be set to <=n>

First enter the calibration password as described in section 3.6.2.

#### Then:-



## 3.6.5 Comparison Calibration

Comparison calibration is most appropriate when calibrating the indicator against a second reference instrument.



Figure 3-5: Comparison Calibration

#### 3.6.6 To Calibrate by Comparison with an External Reference

In this case the process calibration points are not entered ahead of performing the calibration. The input may be set to any value and, when the system is stable, a reading is taken from the reference measurement device and entered into the indicator. The indicator stores both this new target value and the actual reading taken from its input.

The process is repeated at a different value, with the indicator storing both the new target value and the reading taken from its input.

First enter the calibration password as described in section 3.6.2.

Then:-



The indicator is now calibrated against the reference source. When complete the indication returns to the HOME display.

#### 3.6.7 Manual Calibration

In some installations a single offset (section 3.5.1) over the whole range may not be satisfactory. What is required is a method of applying independent offsets to both the lower end and higher end of the input range. An example might be to compensate for known errors in a sensor or sensor input connections but without changing the factory set calibration.

This feature is available in Configuration level in the 2408i indicator by configuring the 'type of calibration' (**LYPE**) in the Input List (iP) to Manual **mHn** (section 4.5.2). This two point offset applies a straight line fit between the low offset point and the high offset point as shown in the graph below. Any readings above or below the two calibration points will be an extension of this line. For this reason it is best to calibrate with the two points as far apart as possible.

#### Example:

Indicator input configured for mV.

A minimum input of 0.0mV to read 0. A maximum input of 10.0mV to read 1000.

In configuration level  $i \Pi PL = 0.0$ ,  $i \Pi PH = 10.0$ , UAL = 0, UAL = 1000

Due to known errors in the transducer or it's connections an output from the transducer of 0.05mV should read 0 on the indicator and an output from the transducer of 10.2mv should read 1000 on the indicator. User offsets can be set up as follows:-



Figure 3-6: High and Low Offsets

In Full access level enter the calibration password as described in section 3.6.2.



The above example shows an indicator configured for mV but the same procedure can be used for other input sensors including thermocouple and PRT sensors.

## 3.6.8 Auto-Tare or Display Zero

The auto-tare (display zero) function is used, for example, when it is required to weigh the contents of a container but not the container itself.

The procedure is to place the empty container on the weigh bridge and 'zero' the controller. Since it is likely that following containers may have different tare weights the auto-tare feature is always available in the indicator at Operator access level.

The effect of auto-tare is to introduce a DC bias to the measurement, as shown in Figure 3-6 below.



#### Figure 3-7: Effect of Auto-Tare

The procedure to initiate tare calibration was described in 2.3.

Note:- A Tare calibration will change the values of 'Scale High' < Scale Low' < Scale Low'

The parameter  $\langle E A F E u \rangle$  sets a fixed offset on the tare value. This may be used, for example, if containers of different weights are placed on a pallet of known weight. This known weight can then be entered in  $\langle E A F E u \rangle$ .

## 3.6.9 To Enter a Fixed Offset to the Tare Value

Do This	The Display You Should See	Additional Notes
1. Press as many times as necessary to select 'CAL I' or 'CAL2' as appropriate	EAL I	
2. Press to scroll to <b>'[AL</b> '	EAL	
3. Press or 💌 to select 'USEF'	USEΓ	
4. Press 🕝 to scroll to <b>'ЕЯ́г Е́</b> ́ш'	ЕА-Е.	
5. Press or to enter the offset value	10	The offset value represents the weight of the pallet for example

If this value is to be changed on a regular basis, it may be convenient to 'promote' the EARE... parameter to the Operator level. The procedure for this is described in section 3.4.

inputs/rising outputs or rising

same curve.

inputs/falling outputs. It is not suitable

Hi are entered first to define the low and high points of the curve. It is not necessary to define all 15 intermediate

points if the accuracy is not required. Points not defined will be ignored and a

straight line fit will apply between the

last point defined and the Input

Hi/Output Hi point.

for outputs which rise and fall on the

#### **Custom Linearisation** 3.7

The linearisation uses a 15 point straight line fit.

Figure 3-7 shows an example of a curve to be linearised and is used to illustrate the terminology used in the parameter list Notes:



Figure 3-7: Linearisation Example



#### 3.7.2 Compensation for Sensor Non-Linearity's

The custom linearisation feature can also be used to compensate for errors in the sensor or measurement system, so that discontinuities in the curve can be calibrated out. Figure 3.8 shows an example of the type of discontinuity which can occur in the linearisation of a temperature sensor.



#### 3.7.1 **Example: To Linearise Input 1**

## 4 CONFIGURATION LEVEL

The 2408/indicator is supplied configured in accordance with the ordering code (see section 5). The configuration of the indicator, as defined by columns 11 to 16 of the order code, can be changed on site, if necessary, to meet the requirements of the installation. Similarly, the positions or types of plug in module can be changed if required. This section describes the procedures to be followed.

## 4.1 Hardware configuration - I/O Modules

Optional plug-in modules are fitted simply by sliding them into the relevant position as shown in Figure 4-1. The connections for these modules are made to the upper row of connector blocks as shown in section 1.3.

When a module is added, removed or changed the indicator will flash hardware error '<HWEr> on power up. To acknowledge this it is necessary to go into configuration level.

- 1. Press either 🗅 or 🕝 until <ConF> is displayed.
- 2. Press or to enter the configuration level password passcode (factory default 2)
- 3. Press either or again and the hardware error is acknowledged

The full list of modules available is shown in the ordering code.



Figure 4-1: View of the Plug-in Modules

## 4.2 Software configuration

Configuration level allows you to set up parameters in the indicator which defines how it will operate. Examples are:-

- The configuration of the alarms
- The digital input functions
- The relay output configuration
- The configuration of the modules
- The passwords

Parameter tables in this section give the full list of configuration parameters.

#### 4.2.1 To Select Configuration Access Level

Do	o This	This Is The Display You Should See	Additional Notes
1.	From any display press bases as many times as necessary to access the <b>'Access List'</b> header	ACCS	If or are pressed the word <li 5l=""> is displayed for 2 secs</li>
2. 3.	Press 🕑 to show < <b>EadE</b> > Press 🔍 or 🔺 to enter the passcode	<sup>2 secs</sup> PASS <b>CodE</b>	The factory default passcode is < 1> <pr55> will be displayed momentarily when the correct password has been entered In the special case that the passcodes have been configured as &lt;0&gt;, it will not be necessary to enter a passcode</pr55>
4. 5.	Press to show < Loto > Press or to select <conf> level</conf>	2 secs	
6. 7.	Press to show < <b>LonF</b> > Press or to enter the configuration level passcode	2 secs PASS ConF	The configuration factory default passcode is <2> ' <pass> will be displayed momentarily when the correct password has been entered In the special case that the passcodes have been configured as &lt;0&gt;, it will not be necessary to enter a passcode</pass>

The indicator is now in configuration level

## 4.3 Location of Parameters - From Indicator Block Diagram

The indicator consists of a number of internal function blocks connected together. Each function block has a number of parameters found in lists to which the user has access. The block diagram shows location of these parameters within the indicator.



### 4.4 Navigation diagram (configuration level)

The navigation diagram shows the location of configuration parameters.

- A. Press 🕒 to step across the list headings. This is a continuous list.
- B. Press 🕝 to step down the parameters within a particular list. You will eventually return to the list heading.
- C. Press 🚺 to view the value of a selected parameter. Keep pressing to decrease the value.
- D. Press 🔺 to view the value of a selected parameter. Keep pressing to increase the value.

The diagram below shows the full list of possible parameters. In practice, the parameters that appear will depend upon the configuration of your particular indicator .





## 4.5 Configuration Parameter Tables - All indicators

The tables in this section list the parameters available for the fixed functionality of the indicator.

## 4.5.1 Instrument configuration list



, u2F	<u>Inst</u> rument list	Option	Meaning	Default setting	Customer setting
uni E	To select display <u>unit</u> s	<u> </u>	<u>C</u> elsius	Defined by the	
		of	<u>F</u> ahrenheit	ordering code,	
		┍┢	<u>K</u> elvin	otherwise <sup>D</sup>	
		попЕ	<u>None</u> (for linear inputs)		
dec p	<b>IECP</b> To set the number of <u>dec</u> imal <u>places</u> in the display		None	Defined by the ordering	
			One	code, otherwise <b>חחחח</b>	
			Тwo		
		חחתח	Three		
Ac.bu	To enable Front panel	EnAP	Button enabled	EnAb	
	<u>Ack</u> /Reset button	di SR	Button disabled		

## 4.5.1.1 Example: To Change the Number of Decimal Places in the Display

D	o This	This Is The Display You Should See	Additional Notes		
Ent	Enter configuration level as described in section 4.2.1.				
1.	Press 🕒 until the <b>'Instrument</b> <b>List</b> ' header is shown	, n5F			
2.	Press 👉 until < <b>dEc P</b> > is shown	2 secs ער חחת ה	The display will return to <b><dec< b=""><b>P&gt;</b> after</dec<></b> approximately 2 seconds		
3.	Press 🔽 or 🔺 to move the decimal point position	dEc.P			

#### 4.5.1.2 Example: To Disable the Front Panel Ack/Reset Button

D	o This	This Is The Display You Should See	Additional Notes		
Ent	ter configuration level as described	in section 4.2.1.			
1.	Press 🕒 until the <b>'Instrument</b> List' header is shown	, n5F			
2.	Press 🕑 until < <b>Ac bu</b> > is shown	² secs ✓ dı 5A	🕞 The display will return to <b>ிட bu&gt;</b> after approximately 2 seconds		
3.	Press 🔽 or 🔺 to select disabled	Нс.Ьи			

## 4.5.2 Sensor Input Configuration List

, P						
G						
• • P	Sensor Input	Option	Meaning		Default setting	Customer
, nPE	To configure <u>inp</u> ut <u>type</u> See also example 4.4.2.1. NOTE: <i>After selecting an input</i> <i>type, do_not forget to</i> <i>adjust the setpoint limits in</i> <i>Full Access level.</i>	J£c +£c L£c r£c b£c n£c ££c 5+r	<u>J</u> thermoo <u>K</u> thermoo <u>R</u> thermoo <u>B</u> thermoo <u>N</u> thermoo <u>T</u> thermoo S thermoo	couple couple couple couple couple couple couple	Defined by the ordering code, otherwise <b>htc</b>	setting
		PL 2 nonE rtd mU uoLt mA Sr U Sr A	Platinell II Custom d 100Ω Plat Linear mil Linear vol Linear mil Square rc Square rc	lownloaded input tinum resistance thermometer lli <u>v</u> olt <u>t</u> age lli <u>a</u> mps pot <u>v</u> olts pot milli <u>a</u> mps	* If a different custom input is supplied, none will be replaced by the reference number shown in the ORDERING CODE section 5	
	See 15-point EuSE list	mUE UE mAE	16-point <u> </u> 16-point <u> </u> 16-point <u> </u>	<u>m</u> illi <u>v</u> olt <u>c</u> ustom linearisation ⊻oltage <u>c</u> ustom linearisation <u>m</u> illi <u>a</u> mp <u>c</u> ustom linearisation		
]L ]	<u>Cold junction</u> <u>compensation (CJC does</u> not appear for Process or RTD inputs. For process see 'Linear input scaling' below	Auto 0°C 45°C 50°C 0FF	<u>Auto</u> mation <u>0°C</u> exter <u>45°C</u> exter <u>50°C</u> exter No cold in	c compensation nal reference ernal reference ernal reference	Яисо	
l mP	Input <u>imp</u> edance threshold for sensor break alarm	DFF Auto Hi Hi Hi	Sensor br 1.5KΩ 5KΩ 15KΩ	eak alarm disabled If the sensor impedance exceeds this value, sensor break alarm activates	Яисо	
Linear in ∐> or <	hput scaling (-9.99 to +80.00m Sr A> are chosen as the inpu	<b>V).</b> These p It type. This	arameters a allows for t	ppear after  whenever he low and high displayed valu	r <b><mu></mu></b> , <b>&lt;⊔□LE</b> >, < es to be set up again:	m <b>A</b> >, < <b>5</b> ┏ st the
E YPE	onding electrical input values. Type of calibration (see 3.3.5.)	OFF Shnt Ld[ [mP mAn		Off Shunt Load Cell Comparison Manual		
bAnd	nd       Settling band.       D-99.99       D.5         The indicator automatically determines when the input has become stable by continuous sampling. When the average value between two consecutive samples is within the settling band the indicator will then allow calibration to take place. If readings are not stable within this period the indicator will abort the calibration       D.9					
The follo example	owing parameters appear for p e 4.5.2.2.	rocess inpu	ts and allow	the display to be calibrated to	the electrical input. S	See also
I nPL I nPH	Electrical <u>inp</u> ut <u>l</u> ow Electrical <u>inp</u> ut <u>h</u> igh	- 100.0 to 0.0 to 0.0 to	o 100,0 mV 20,0 mA 10,0 Volts		00 1000 if mV 200 if mA 100 if volts	
UAL L	Displayed <u>val</u> ue <u>l</u> ow	-9999 to	99999		Defined by the SP limits in ordering	
UAL H	Displayed <u>val</u> ue <u>h</u> igh	<b>-9999</b> to	99999		Defined by the SP limits in ordering code, else	

#### 4.5.2.1 Example: To Select a Different Thermocouple Type

D	o This	This Is The Display You Should See	Additional Notes
	Enter co	onfiguration level as described in	section 4.2.1.
1.	Press 🕒 until the <b>'Input List'</b> header is shown	, <b>P</b>	
2.	Press 👉 until < <b>, nPL</b> > is shown	<sup>2 secs</sup>	The display will return to <1 nPL>
3.	Press 💌 or 🔺 to select the input type	, nPE	

#### Notes:

The next parameter is cold junction compensation,  $\langle L JL \rangle$ . It is used to compensate for ambient temperature changes measured at the point at which the thermocouple (or compensating) cable connects to the indicator. Automatic, Auto, measures the temperature at the rear terminals and compensates for any ambient temperature changes. It will only be necessary to change the  $\langle LJL \rangle$  parameter if an external temperature reference source is to be used.

Sensor break is measured by the impedance, < mP >, of the sensor circuit and an alarm is given if this is greater than a set amount. For thermocouples set this to  $< H_{LL} L_{D} >$ . For certain types of sensor its working impedance may be greater than the 1.5K $\Omega$  set by Auto. It will only be necessary to change < mP > if this type of sensor is to be used.

#### 4.5.2.2 Example: To Adjust Display Reading for a Process Type Input

This example is 4 - 20mA input to read 0 to 100 on the display



#### 4.5.3 Alarm Configuration

Alarms are used to alert an operator when the process value has exceeded a pre-set level or when some other fault condition has occurred. They normally switch an output - usually relay - to provide an interlock on a machine/process or audio/visual indication to an operator.

The Model 2408/has four internal 'soft' alarms which are configured in the  $\langle \mathbf{RL} \rangle$  list below. A soft alarm means indication only. To make a soft alarm activate a physical output it must be 'attached' to that output. See: section 4.5.8. 'Relay Output Configuration'

#### ALARM DEFINITIONS: The following alarm types can be configured:

Full Scale High	The Process Value is above a set high level
Full Scale Low	The Process Value is below a set low level
Deviation band	The difference between setpoint and the process value is outside a set band
Deviation high	The difference between setpoint and the process value is above a set value
Deviation low	The difference between setpoint and the process value is below a set value

Rate of change The Process Value is changing faster than a set rate

AL	<u>Al</u> arm list	Option	Meaning	Default setting	Customer setting			
AL I	To select <u>Al</u> arm <u>1</u>	DFF	The alarm is disabled	Defined by the	,	Alarm ı	numbe	r
	Туре	FSL	<u>F</u> ull <u>S</u> cale <u>L</u> ow alarm - main process value	ordering code,	1	2	3	4
		FSH	<u>F</u> ull <u>S</u> cale <u>H</u> igh alarm - main process value	otherwise <b>DFF</b>				
		dEu	Deviation band alarm - main process value					
		dHi	Deviation High alarm - main process value					
		dLo	Deviation Low alarm - main process value					
		du l	Deviation band alarm - input 1					
		dH I	Deviation High alarm - input 1					
		dL I	<u>D</u> eviation <u>L</u> ow alarm - input 1					
		du2	Deviation band alarm - input 2					
		GH5	Deviation High alarm - input 2					
		dL2	Deviation Low alarm - input 2					
		FL2	<u>F</u> ull Scale <u>L</u> ow alarm on Process Value input <u>2</u>					
		FH2	<u>F</u> ull Scale <u>H</u> igh alarm on Process Value input <u>2</u>					
		LSP	Master <u>S</u> et <u>p</u> oint <u>L</u> ow alarm					
		HSP	Master <u>S</u> et <u>p</u> oint <u>H</u> igh alarm					
		FL I	<u>F</u> ull scale <u>l</u> ow alarm on linearised input <u>1</u>					
		FH I	<u>F</u> ull scale <u>h</u> igh alarm on linearised input <u>1</u>					
		rAF	Rate of change alarm, minutes - main PV					
		r AS	Rate of change alarm, seconds - main PV					
		rt l	Rate of change alarm, minutes - input 1					
		r51	Rate of change alarm, seconds - input 1					
		r£2	Rate of change alarm, minutes - input 2					
		r52	Rate of change alarm, seconds - input 2					
LEch	To select alarm	по	<u>No</u> n-latching	по				
	latching type	YES	Latched with automatic resetting (See note 1)					
		Lunt	Event output (See note 3)					
		mHn	Latched with <u>man</u> ual resetting (See note 2)					
bLoc	To select alarm <u>bloc</u> king	ne YES	No blocking Blocked until first good (See note 4)	חח				
5br.E	To inhibit process	di SR	Disabled. Inhibits alarms (See note 5)	EnAb				
	alarms in sensor break	EnAb	Enabled. Alarms operate when in sensor break					
The abo	ove sequence is rep	eated for:	$\langle \mathbf{AL} \ 2 \rangle$ (alarm 2), $\langle \mathbf{AL} \ 3 \rangle$ (alarm 3) and	$\langle \mathbf{H} \mathbf{L} \mathbf{H} \rangle$ (alarm 4)				

Note 1 Automatic Resetting means that, once the alarm has been acknowledged, it will automatically clear when it is no

longer true

Note 2 Manual resetting means that the alarm must first clear before it can be reset

Note 3 **Events** can be used to operate an output in the same way as an alarm but will NOT flash an alarm message, and can be used to trigger external events. For example, an event output could be used to open/close a vent at a pre-set temperature

Note 4 **Blocking Mode.** After power on, the process value must first enter a good state before the alarm becomes active. When once this process has been completed the alarm operates in its normal mode and does not become relevant again until power to the indicator is turned off and on again. This is particularly useful for low alarms which can be 'blocked' while the process is warming up. It is advised that blocking alarms are not used with rate of change alarms

Note 5 **Sbr.t** When this parameter is set to 'Disabled', all alarms from the process will be inhibited should a sensor break condition occur. When Enabled process alarms will be shown (as in previous software versions) even in a sensor break condition.

#### Example: To Configure Alarm 2 to Operate When Input 2 Exceeds A Set Value

D	o This	This Is The Display You Should See	Additional Notes
Ent	er configuration level as describ	ed in section 4.2.1.	
1.	Press D until the <b>'Alarm List'</b> header is shown	AL	
2.	Press 🕢 until < <b>AL 2</b> > is shown	<sup>2 secs</sup>	The display will return to <b>(FL 2</b> > after approximately 2 seconds
3.	Press 🔽 or 🔺 until < <b>FH2</b> > is shown	AL 2	< <b>FH2</b> > is <u>F</u> ull Scale <u>H</u> igh alarm on input <u>2</u>

The next two parameters - Alarm Latching and Alarm Blocking may be set in the same way if they are required.

#### 4.5.4 Alarm Inhibit

The alarm inhibit feature may be used to prevent any alarms from being indicated until a 'noisy' process variable has settled. Alarm inhibit is activated by a digital input on either Digital Input 1 or 2 - see section 4.5.4. When the digital input is turned to OFF any alarms which are active will be displayed. If a delay has been set on the alarm, the delay period will start from the time when the input is turned OFF. Entering Alarm Inhibit resets both the alarm delay timer and latched alarms.

The action of Alarm Inhibit is shown in the diagram below for a Full Scale High Alarm.





#### 4.5.5 2408i Indicator With Alarm Inhibit Timer

2408i indicators fitted with software versions 3 and greater contain an alarm inhibit timer which is used to inhibit alarms for a set period after power-up and when a digital input is closed.

#### 4.5.5.1 Operation

In the 'AL' list in Operator Level there are two parameters associated with the inhibit function see section 3.3.2. These are the alarm inhibit status'  $I \cap AL'$  and the inhibit time ' $I \cap HL'$ '. To adjust the alarm inhibit time:-

Do This	This Is The Display You Should See	Additional Notes
1. In Operator Level, press many times as necessary to select 'AL'	2 secs	Press or to show 'Lı 5L' if required. The display will revert to 'AL' after 2 seconds
<ol> <li>Press  to read 'I nFL'</li> <li>Press  or  to select '□n' or '□FF'</li> </ol>	2 secs	This sets the Alarm Inhibit status: Dn/DFF. The display will revert to 'I nAL' after 2 seconds
<ul> <li>4. Press  to read 'I nHL'</li> <li>5. Press  or  to select the Alarm Inhibit Time</li> </ul>	2 secs	This sets the Alarm Inhibit Time 0 to 999.9 seconds. The display will revert to <b>'I nHL</b> ' after 2 seconds

On power up alarms will be inhibited for the set time. When the inhibit time is set to OFF, the timed inhibit is disabled.

#### 4.5.5.2 Configuration of Digital Inputs for Alarm Inhibit

Two digital input functions can be configured for the alarm inhibit.

#### Permanent alarm inhibit

The permanent inhibit function ' $n \mathcal{R}L$ ' is level triggered. It permanently inhibits all alarms when closed and enable all alarms when open.

Do This	This Is The Display You Should See	Additional Notes
<ol> <li>In Configuration Level, press based as many times as necessary to select 'LR' or 'Lb' - the digital inputs. See also section 4.5.6.</li> </ol>	<sup>2 secs</sup> LA/Lb	Digital input configuration
2. Press  G to read 'Func' 3. Press  ▲ or  ▼ to select 'i nAL'		Level triggered alarm inhibit Please note: when using this function ensure that the inhibit timer is set to OFF.

#### Timed alarm inhibit

The timed inhibit function  $' Em \mathcal{PL}'$  is edge triggered. It will start the inhibit timer when closed and do nothing when opened. Alarms will be inhibited during the timing period at the end of which they will be enabled again.

From stage 1 above:-

Do This	This Is The Display You Should See	Additional Notes
<ul> <li>4. Press  to read  'Func'</li> <li>5. Press  or  to select ', nAL'</li> </ul>	2 secs Func	Timed alarm inhibit

## 4.5.6 Digital inputs 1 and 2 Configuration

LA	Digital input 1	Option	Meaning	Default setting	Customer
LЬ	Digital input 2				setting
ı d	<u>Id</u> entity of input	רקסר	Logic input	رآما	Read only
Func	<u>Func</u> tion	nonE	Function not configured	nonE	
		rmŁ	<u>R</u> e <u>m</u> o <u>t</u> e setpoint select		
		Ac AL	<u>Al</u> arm <u>ac</u> knowledge		
		AccS	Select full <u>acc</u> es <u>s</u> level		
		Loc.b	Key <u>loc</u> k (disables all front panel buttons except the ACK/RESET button)		
		uР	Simulate pressing of the 🔺 button		
		dwn	Simulate pressing of the 💌 button		
		Serl	Simulate pressing of the 🕝 button		
		Page	Simulate pressing of the 🛅 button		
		PU.SL	<u>P</u> rocess <u>v</u> alue <u>s</u> e <u>l</u> ect.		
			Closed = input 1 Open = input 2		
		EAr.1	Initiate <u>a</u> utomatic <u>tar</u> e calibration of input <u>1</u>		
		ERr.2	Initiate <u>a</u> utomatic <u>tar</u> e calibration of input <u>2</u>		
		PEL.1	Start the calibration at <u>p</u> oin <u>t</u> 1, normally the <u>l</u> ow point		
		PEL2	Start the calibration at <u>p</u> oin <u>t</u> 2, normally the <u>l</u> ow point		
		PEH. I	Start the calibration at <u>p</u> oin <u>t</u> 1, normally the <u>h</u> igh point		
		PEh.2	Start the calibration at <u>p</u> oin <u>t</u> 2, normally the <u>h</u> igh point		
		, nAL	<u>Al</u> arm <u>in</u> hibit (often used in conjunction with transducer calibration to prevent alarms during the calibration process)		
		PHLd	<u>P</u> eak <u>hold</u>		
		HLd I	Sample and <u>H</u> o <u>ld</u> on PV input <u>1</u>		
		HL95	Sample and <u>H</u> o <u>ld</u> on PV input <u>2</u>		
		UEAL	Enables calibration access for EAL 1 and EAL2 lists		

## 4.5.6.1 Example: To Configure Digital Input 'A' for Tare Calibration

Do This This Is The Display You Should See			Additional Notes						
Ent	Enter configuration level as described in section 4.2.1.								
1.	Press 🕒 until the <la> List' header is shown</la>	LA							
2.	Press 👉 until the < <b>Func</b> > is shown		The display will return to <b>Func</b> after approximately 2 seconds						
3.	Press 🔽 or 🔺 until < <b>LAr. I</b> > is shown	Func	When a connection is made between rear terminals LC and LA a tare calibration is initiated.						
 TL	I I	, and a matter of a sure in the Distinct I	· · · · · · · · · · · · · · · · · · ·						

The same procedure applies to any other option shown in the Digital Inputs table and also to the second digital input which uses list  $<\!\!Lb\!\!>$ .

#### 4.5.7 Peak Hold and Sample and Hold

**Peak Hold** logs the maximum and minimum values that the indicator reads during a particular process. The peak hold value can be displayed as the main front or back display parameter, as described in section 2.1.2.

Sample and Hold logs the reading at the moment that the digital input becomes true.

Both functions are initiated by turning digital input 1 or digital input 2 to ON. They are edge triggered, so to reset and re-start, the input must be turned OFF and ON again, as detailed in Figure 4.5 below.

The values may be read in two ways:-

- 1. From Information List </ nFo> as:-
  - Lo[.L Minimum process variable
  - LoG.H Maximum process variable

These values are reset when the parameter  $\langle rE5L \rangle$  in the  $\langle nF_{D} \rangle$  list is turned to  $\langle \Psi E5 \rangle$ , or the indicator power is cycled.

2. Maximum and minimum values can be promoted to the main front or back display as <**PUH** > or <**PULo**>, see section 2.1.2. They are reset when the power to the controller is cycled or by setting the values of <**LoLI**> and <**LoLH**> to zero in the <**IIFo**> list.



Time

Figure 4-5: Action of Sample and Hold and Peak Hold

## 4.5.8 Relay Output 1 Configuration

The controller can be supplied so that Relay 1 will operate when a particular alarm occurs. This will be defined in the order code, see section 5.

This list defines which of the internal 'soft' alarms are attached to relay output 1. It is possible to attach more than one alarm to operate this relay. The procedure is described below:-

AA					
<u>ی</u>					
AA	Relay output 1	Option	Meaning	Default setting	Customer setting
' q	<u>Id</u> entity of output	гELY	Relay	rELY	Read only
Fune	<u>Func</u> tion of output	попЕ	None Output disabled	막민	
		d, G	Digital alarm output. Output enabled		
SEnS	<u>Sens</u> e of the output.	пог	Normal (relay energised in alarm)	ιΠU	
		i nu	Inverted (relay de-energised in alarm)		
To Attach	Alarms to the Relay Outpu	t.			
Any comb	ination of the following alar	ms can be att	ached to relay output 1.		
Press 🕑	to select a particular alarm.				
Press 🔺 o	or 💌 to select <b>YE5</b> if you v	vant it to activ	ate the relay. Select <b>nn</b> to disconnect a given a	larm.	
These para	ameters only appear if <b>Fur</b>	nc = dı G			
*	Alarm <u>1</u>	YES/no -	Attaching Alarms to the relay	YES	
2*	Alarm <u>2</u>	YES/no -		по	
]*	Alarm <u>3</u>	YES / no	Kelay output 1	по	
4*	Alarm <u>4</u>	YES/no -		по	
Sbr	<u>S</u> ensor <u>br</u> eak alarm	YES / no		no	
SPAn	Span The Process	YES/no		по	
	value exceeds the display limits				
r m H F	<u>Remote failure</u> . Either	YFS/nn		00	
,	PDS <u>rem</u> o <u>t</u> e setpoint				
	input, OR 2nd analogue		//		
	Input open circuit		L/ /		
	Now alarm		/	ПО	
пш.ЛĹ		סח / כשי		סח	

1. The three dashes correspond to the alarm type set in the <AL> list. If the alarm is disabled, <AL I> or <AL 2> or <AL 3> or <AL 4> will be shown.

### 4.5.8.1 Example 1: To Attach Alarm 1 to Relay Output AA

It is recommended that an external device is connected so that an alarm condition is indicated when the relay is de-energised. In this way if the indicator is removed or its power is removed an alarm is indicated.



To achieve this set relay sense to inverted operation.



#### 4.5.8.2 Example 2: To Operate Relay 1 of a Dual Relay Output Module Fitted in Slot 2 when Both Alarms 2 and 3 are Active

The wiring should be as shown in Section 1.3 using rear terminals 2A and 2B

	e winnig should be as shown in se	ction 1.5 daing real terminals ZA a	110 20
D	o This	This Is The Display You Should See	Additional Notes
Ent 4.4	er configuration level as described in 3.1.	section 4.2.1. and configure Alarms 2 a	and 3 to the required types - see example
1.	Press buntil the <b>&lt;2A&gt; List'</b> header is shown	R5	
2.	Repeat steps 3 to 5 above		
3.	Press 🕝 until the < <b>2</b> > is shown		The display will return to <b>&lt;2&gt;</b> after approximately 2 seconds
4.	Press 🔽 or 🔺 to select < <b>YE5</b> >	2	
5	Proce G until the <> is	2 sers	The display will return to  after approximately 2 seconds
5.	shown		Relay 1 of module 2 will operate when either Alarm 2 or Alarm 3 is active
6.	Press 🔽 or 🔺 to select < <b>YE5</b> >	<u> </u>	This procedure can be repeated for all alarms which require to operate an output relay.
			Notes: Logic module outputs can also be attached to alarms
			Do not forget to say < <b>nD</b> > to any alarm which may already be attached to an output if it is not required.
			+

## 4.6 Configuration Parameter Tables - plug in modules

## 4.6.1 Communications Module

The 2408/indicator can be fitted with the following digital communications modules:-

Protocol	Module Fitted	Order Code
ModBus	2-wire RS485	2YM
	4-wire RS422	2FM
	RS232	2AM
El-Bisynch	2-wire RS485	2YE
	4-wire RS422	2FE
	RS232	2AE
DeviceNet		2DN

#### 4.6.2 Communications Parameters



HA	Communications Module configuration	Option	Option Meaning		Customer setting
١d	<u>Id</u> entity of module	cm5	Communications	cm5	Read only
Func	Function (selects the	nction (selects the mad Modbus protocol			
	comms.	El .bi	El-Bisynch protocol		
protocol) dnEL		Devicenet - if the Devicenet module is fitted			
		ProF	Profibus - if the Profibus module is fitted		
ЬЯлд	Selects the baud rate	1200, 24	1 <b>00, 4800, 9600, 19.20</b> (19,200)	9600	
ЧЕГА	Response delay: required	no	No delay	по	
	adapters	YES	10mS delay		
Prty	Selects the parity	попЕ	No parity	nonE	
	(Modbus only)	EuEn	Even parity		
		Odd	Odd parity		
rES	Selects the resolution	Full	<u>Full</u> resolution	Full	
	(Modbus and Profibus only)	Int	Integer resolution		

## 4.6.3 PDS input Module

JR

لم ا					
JR	Communications Module configuration	Option	Meaning	Default setting	Customer setting
, d	<u>Id</u> entity of module	PdSi	PDS input	Pd5,	Read only
Func	Function	nonE SP, P	No function configured Setpoint input (to accept an input signal from a master source such as a controller with pds output)	nonE	
UALL	Setpoint low value	-9999 to 99999		0	
UALH	Setpoint high value	-9999 to 99999		0	

### 4.6.3.1 Example: To configure Function, Baud Rate, Resolution and Node Address:-

Do This	This Is The Display You Should See	Additional Notes			
1. Press as many times as necessary to select 'HA'.	HA EonF	This is the position in which a digital communications module is fitted			
2. Press 🔄 to read 'ı <b>d</b> '	, d 5	If the module is present יו d' = [m5 (digital communications) or יחםחE' if the module is not present			
<ul> <li>3. Press to read 'Func'</li> <li>4. Press to read 'bflud'</li> </ul>	Func	If Modbus or El Bisync module is fitted, 'Func' = 'mad' or 'El b, ' If Profibus module is fitted, 'Func' = 'ProF' If the DeviceNet module is fitted, 'Func' = 'dnEL' These ware be read only			
5. Press or to select the baud rate	6Aud	For Modbus or El Bisync baud rate can be set to 1200, 2400, 4800, 9600, or 19,200 For Profibus baud rate is set automatically to a maximum of 1M5 For Devicenet baud rate can be set to 125(K), 250(K) or 500(K)			
<ul> <li>6. Press  to read 'rE5</li> <li>7. 'Press  or  to select 'FuLL' or 'I nL'</li> </ul>	rES Full	'Full' the decimal point position is implied, eg 100.1 is transmitted as 1001. 'I nl' rounded to the nearest the integer value			

## Node Address is set up in Full Access level

Exit configuration level as described in the Installation and Operation Handbook, Chapter 6. Then:-

Do This	This Is The Display You Should See	Additional Notes				
1. Press ⓑ as many times as necessary to select ' <b>⊂ ⋒5</b> '.	<b>cm5</b> L, St					
<ol> <li>Press to read 'Addr'</li> <li>Press or to select the address for the instrument</li> </ol>	Rddrs	Valid addresses are from 0 - 63				
4. Press	nw.5L run	Indicates the network status:- 'רשח' = network connected and operational 'רשש' = network connected but not operational DFFL' = network not connected				

#### 4.6.4 DeviceNet Communications

The following is applicable to DeviceNet only.

#### 4.6.4.1 The EDS File

The EDS (Electronic Data Sheet) file for the 2408*i* is named 2400.EDS and is available from your supplier, or electronically by going to Web site (www.eurotherm.com). The EDS file is designed to automate the DeviceNet network configuration process by precisely defining vendor-specific and required device parameter information. Following a data sheet metaphor, the EDS file describes a device's configurable parameters, including its legal and default values and the public interfaces to those parameters. Software configuration tools utilize the EDS files to configure a DeviceNet network.

#### 4.6.4.2 ODVA Compliance

This interface has been tested to comply with the full requirements of the ODVA (Open DeviceNet Vendors Association) conformity tests.

Terminal Reference	CAN Label	Color Chip	Description
НА	V+	Red	DeviceNet network power positive terminal. Connect the red wire of the DeviceNet cable here. If the DeviceNet network does not supply the power, connect to the positive terminal of an external 11-25 Vdc power supply.
НВ	CAN_H	White	DeviceNet CAN_H data bus terminal. Connect the white wire of the DeviceNet cable here.
HC	SHIELD	None	Shield/Drain wire connection. Connect the DeviceNet cable shield here. To prevent ground loops, ground the DeviceNet network in only one location.
HD	CAN_L	Blue	DeviceNet CAN_L data bus terminal. Connect the blue wire of the DeviceNet cable here.
HE	V-	Black	DeviceNet network power negative terminal. Connect the black wire of the DeviceNet cable here. If the DeviceNet network does not supply the power, connect to the negative terminal of an external 11- 25 Vdc power supply.
HF			Connect to instrument earth

#### 4.6.4.3 DeviceNet Wiring Connections

Note: Power taps are recommended to connect the DC power supply to the DeviceNet trunk line. Power taps include:

A Schottky Diode to connect the power supply V+ and allows for multiple power supplies to be connected.

• 2 fuses or circuit breakers to protect the bus from excessive current which could damage the cable and connectors.

The earth connection, HF, to be connected to the main supply earth terminal.



Figure 4-7: Typical DeviceNet Wiring Diagram

#### 4.6.5 Module 1, 2 and 3 Configuration Lists

The identity of a module fitted in slots 1, 2 or 3 is shown by the first parameter in the module lists.

- If the module is a single output only channel  $\langle H \rangle$  is shown
- If the module is a dual output channel  $\langle R \rangle$  and channel  $\langle L \rangle$  are shown
- If the module is a triple output Channel  $\langle H \rangle$ , channel  $\langle b \rangle$  and channel  $\langle L \rangle$  are shown

Module configuration lists are summarised below:-



Note: Channel 'b' only appears if a dual or triple channel module is fitted. Channel 'L' only appears if a triple channel module is fitted

					Cus	tomer	setting	in each	n chanr	nel num	nber	
Module Parame	ters	Option	Meaning	IA	Ю	IE	2A	26	25	AE	Зь	E
۰d	<u>Id</u> entity	попЕ	Module not fitted									
	of	rELY	<u>Rel</u> a <u>y</u> output									
	module	LoG	<u>Log</u> ic output									
		ריםרן	<u>Log</u> ic or contact closure <u>i</u> nput									
		9C° b	2 <sup>nd</sup> analogue input module (Module 3 only)									
		derE	DC retransmission									
		EPSU	<u>T</u> ransmitter <u>p</u> ower <u>su</u> pply									
		56.50	<u>S</u> train <u>g</u> auge power <u>su</u> pply									

#### 4.6.6 Changeover Relay or Dual Relay Output Module

#### 4.6.7 Triple Logic Output Module

The parameter lists are the same for each of these modules as listed below:-

۰d	<u>ld</u> entity of	rELY	<u>Rel</u> a <u>y</u>	Customer settings in each channel								
	module	LoG	<u>Log</u> ic	IA	Ю	IE	2R	2P	22	AE	ЗЬ	ЭЕ
Func	<u>Func</u> tion of output	nonE di G	Module operation turned off Digital									
SEnS	<u>Sens</u> e of the output	חםר ו חט	חסר Output energises when TRUE									
			Output de-energises when TRUE (default for alarms)									
IfFunc	= nanE no further	parametei	s are shown									
1	Alarm <u>1</u>	YES/n	YES / no									
2	Alarm <u>2</u>	YES / ni	YES / no									
3	Alarm <u>3</u>	YES / ni	Alarms are									
4	Alarm <u>4</u>	YES/n	attached to the									
БЬг	<u>S</u> ensor <u>br</u> eak alarm	YE5 / л same	output in the									
SPAn	<u>Span</u>	YES / ni	way as relay									
rmŁF	<u>R</u> e <u>m</u> o <u>t</u> e <u>f</u> ailure	YES/n	output 1									
, P IF	Input 1 fail	YES / ni	ם									
nwAL	nwAL New alarm YES / no											
The changeover relay output module has a single output so the above parameters are shown under list <- A> only												
The trip	le logic module has	three out	puts so the above paramet	ers are	shown	under	lists' ·	< <b>-</b> 用>, <	< <b>-b</b> >, а	and' <	< <b>-</b> [>	
The dua	l relav module has t	two outpu	ts so the above parameters	are sh	own un	der list	s' <-	H > and	<-[]>			

## 4.6.8 Triple Logic Input or Triple Contact Closure Input Module

The triple logic input module allows further digital inputs in addition to those in the basic instrument. The list of parameters is the same as the fixed digital inputs 1 & 2, section 4.5.6. as follows:-

				Custo	omer se	ettings	in each	chann	el			
				IR	ĺЬ	IE	2R	2Р	22	ЯE	ЗЬ	ЭЕ
' q	<u>ld</u> entity of module	ιοδι	Logic input	Read	only							
Func	<u>Func</u> tion	попЕ	Function not configured									
		rmŁ	<u>R</u> e <u>m</u> o <u>t</u> e setpoint select									
		Ac.AL	<u>Al</u> arm <u>ac</u> knowledge									
		AccS	Select full <u>acc</u> es <u>s</u> level									
		Loc.b	Key <u>loc</u> k (disables all front panel buttons except the ACK/RESET button)									
		uP	Simulate pressing of the button									
		dwn	Simulate pressing of the <b>v</b> button									
		Serl	Simulate pressing of the									
		PAGE	Simulate pressing of the button									
		PU.SL	$\frac{P}{\text{rocess }\underline{v}\text{alue }\underline{s}\text{elect.}}$ Closed = input 1									
		EAr.1	Initiate <u>a</u> utomatic <u>tar</u> e calibration of input <u>1</u>									
		EAr.2	Initiate <u>a</u> utomatic <u>tar</u> e calibration of input <u>2</u>									
		PEL.1	Start the calibration at <u>point</u> 1, normally the <u>l</u> ow point									
		PEL.2	Start the calibration at <u>point</u> 2, normally the <u>l</u> ow point									
		PEH. I	Start the calibration at <u>point</u> 1, normally the <u>h</u> igh point									
		PEh.2	Start the calibration at <u>point</u> 2, normally the <u>h</u> igh point									
		ı n.AL	<u>Al</u> arm <u>in</u> hibit									
		PHLd	<u>P</u> eak <u>h</u> o <u>ld</u>									
		HL4 I	Sample and <u>H</u> o <u>ld</u> on PV input <u>1</u>									
		HL95	Sample and <u>H</u> o <u>ld</u> on PV input <u>2</u>									
		UEAL	Enables calibration access for <b>EAL 1</b> and <b>EAL2</b> lists									
The trip	ole logic or triple	e contact c	closure module has three inputs	so the	above	param	eters a	re show	n unde	er lists		
< <b>-</b> H>,	< <b>-b</b> >, and <-	[>										

#### 4.6.9 DC input Module

#### The DC Input module can only be fitted in slot 3. The following parameters appear:-

Module	Parameters	Option	Meaning	Customer settings 3				
۰d	<u>ld</u> entity of module	9C° b	<u>DC inp</u> ut	Read only				
Func	<u>Func</u> tion	полЕ	No function. Input used for monitoring and alarm only					
		r SP	<u>Remote setpoint input.</u> When selected this becomes the setpoint f	or deviation alarms.				
			In $$ access level, set Remote SP Enable, $$ = $$	(Remote SP selected)				
		Hı	Process Value = the <u>hig</u> hest of Input 1 and input 2 is displayed in n normal operation the display cannot be switched between 'front' a reading shows the highest or lowest value only.	ormal operation. In nd 'back' views. The				
		Lo	Process Value = the lowest of Input 1 and input 2 is displayed in normal operation. In normal operation the display cannot be switched between 'front' and 'back' views. The reading shows the highest or lowest value only.					
		FEn	Derived value. Process Value = $(\langle F. I \rangle \times \text{Input 1}) + (\langle F. I \rangle \times \text{Input 2})$ , where $\langle F. I \rangle$ and $\langle F. I \rangle$ are scalars found in the $\langle I P \rangle$ list in Full Access level. Refer to section 3.3.4. for an example of differential measurement.					
		SEL	Select input 1 or input 2 via comms, a digital input, or in the Operator $< P >$ list. If a digital input is configured use the parameter $$ . If the input is selected through the Operator list in Full Access use the parameter $$ <u>Transition region between</u> $< P. I >$ and $< P2 >$ , set by $$ and $$ in Operator Level. See example 4.6.7.1.					
		ErAn						
lf <fun< td=""><td>nc&gt;=<none< td=""><td>no further p</td><td>parameters are shown.</td><td></td></none<></td></fun<>	nc>= <none< td=""><td>no further p</td><td>parameters are shown.</td><td></td></none<>	no further p	parameters are shown.					
When <	When $\langle F_{unc} \rangle \neq \langle nunc \rangle$ , input 2 parameters are shown in the Input List in Full access level							
The par option	The parameters that follow are the same as those in the $< P >$ configuration list plus $< H_1 L_n > -$ the high impedance input option							
, nPE		Refer to <	p P> list section 4.5.2. plus the following parameter	Customer settings				

ı nPE		Refer to <ı	Refer to $<$ $P$ > list section 4.5.2. plus the following parameter (		
		Hiln	0 to 2volt high impedance input		
JL J		Refer to <₁	P>list		
l mP					
I nPL					
╎╓ҎӉ					
UALL					
UAL H					
FAbe	<u>Type</u> of	oFF	Off		
	calibration	Shne	Shunt		
		LdE	Load Cell		
		EmP	Comparison		
		mAn	Manual		
bAnd	Settling <u>band.</u>	0- 99.99 (Default 0.5)	The indicator automatically determines when the input has become stable by continuous sampling. When the average value between two consecutive samples is within the settling band the indicator will then allow calibration to take place. If readings are not stable within this period the indicator will abort the calibration		
The DC	input module	has a single	input so the above parameters are shown under list $< \exists A >$ only		

#### 4.6.9.1 Example: Input 1 and Input 2 are Configured for Transition

An example of the use for this could be the measurement of temperature over a wide range. The lower temperatures may be measured by a base metal thermocouple connected to Input 1 and higher temperatures may be measured by a pyrometer or precious metal thermocouple connected to input 2. The reason for such a combination is to provide the most accurate readings over the full temperature range where the thermocouple cannot be used at high temperatures and the pyrometer is too insensitive at low temperatures to provide an accurate reading.

The thermocouple may be withdrawn, to prevent damage to it, using a high alarm set around the upper limit of the thermocouple.



Figure 4-8: Input 1/Input 2 Transition

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De	o This	This Is The Display You Should See	Additional Notes							
	A. Configure the DC Input Module fitted in slot 3 for transition function									
1.	Press 🕒 until the < 🗷 List header is shown	RE								
2.	Press until <b>Func</b> > is shown	<sup>2 secs</sup>	ت The display will return to < <b>Func</b> > after approximately 2 seconds							
3.	Press or to select < Ernn>	Func								
	B. Configure an alarm as a full scale high event									
1.	Press 🕒 until the <b>'Alarm List'</b> header is shown	AL								
2.	Press 🕝 to select alarm 1, 2, 3, or 4 as appropriate	<sup>2 secs</sup>	This configures alarm 1 for full scale high							
3.	Press 🔽 or 🔺 to select <f5h></f5h>									
4.	Press to select <lech></lech>		This configures alarm 1 for an event so that an alarm message is not							
5.	Press $\checkmark$ or $\checkmark$ to select $<$ EunE>	LECH	displayed as the PV exceeds the alarm setpoint.							
	C. Attach the alarm	to a relay output as described in exam	nples 4.4.5.1 or 4.4.5.2.							
C	D. Exit configuration level and enter F	ull access level to set the transition val	ues and full scale high alarm (event) setpoint							
1.	Press 🕒 until the <b>'Input List'</b> header is shown	, P								
2.	Press ن until the < <b>Lو P</b> > is shown									
3.	Press or to set a level at which the sensor on input 1 is to be phased out	Lo, P								
4.	Press 🕝 until the < <b>H</b> , J <b>P</b> > is shown	2 secs	If $< L_{0}$ P> is set to the same value as							
5.	Press or to set a level at which the sensor on input 2 is to be phased in	<   1 100   Hi j P	< <b>H</b> , J ₽> the displayed reading will jump from Input 1 to input 2 at this value.							
6.	Press 🕝 until the <f 1=""> is shown</f>	2 secs	<f. i=""> and <f.2> are constants to achieve a derived PV</f.2></f.>							
7.	Press 🔽 or 🔺 to set a multiplying factor on input 1 if necessary	< <u>0.5</u> F I	where PV = < <b>F</b> . <b>i</b> > x input 1 + < <b>F</b> . <b>i</b> > x input 2 As the displayed reading, in normal							
8.	Repeat for <b><f2< b="">&gt;</f2<></b>		operation, moves between Input 1 and input 2 it will do so in a controlled manner. Some experiment may be necessary with the four parameters to achieve ideal settings.							
9.	Press 🕒 until the <b>'Alarm List'</b> header is shown	RL								
10.	Press 👉 until the < <b>AL I</b> > is shown	2 secs								
11.	Press or to set the level at which the base metal thermocouple is to be removed									
			•							

#### 4.6.10 DC Retransmission Module

The following parameters appear.

Module	Parameters	Option	Meaning		Customer setting	Is
۰d	<u>Id</u> entity of module	derE	DC retransmission	IA	2A	AE
Func	<u>Func</u> tion	попЕ	<u>None</u> configured			
		РU	<u>P</u> rocess <u>v</u> alue retransmission			
		ωSP	<u>S</u> et <u>p</u> oint retransmission			
		Err	Error from setpoint retrans.			
		1 P.1	<u>Input 1</u> retransmission			
		1 P.2	<u>Input 2</u> retransmission			
IfFunc	= <b>חםח</b> no further para	meters are	shown			
UALL			Retransmission value low			
UAL H			Retransmission value High			
Uni E			Electrical output units u=LL = Volts, <b>m</b> H = milliamps			
Out.L	-		Minimum electrical output			
Out H	:H		Maximum electrical output			
The DC	retransmission module	has a single	e output so the above parameters	are shown und	er list <b>-A</b> only	

#### 4.6.10.1 Example: To Scale the DC Retransmission Output

The retransmission output can be scaled so that the output value corresponds to the range of the signal to be transmitted.

Figure 4.5 shows an example where the retransmitted signal is  $\langle PU \rangle$  or  $\langle wSP \rangle$  and an electrical output of 4-20mA represents a displayed value of 20.0 to 200.0 units.



Figure 4-9: Scaling a Retransmission Output

#### 4.6.11 Strain Gauge Transducer Supply

The following parameters appear:-

Module Parameters		Option	Meaning	Customer settings			
				IA	2A	AE	
' q	<u>ld</u> entity of module	56.50	<u>S</u> train <u>G</u> auge <u>su</u> pply				
Func	<u>Func</u> tion	попЕ	nE <u>None</u>				
		, P 1	Bridge supply for <u>inp</u> ut <u>1</u>				
		، ۲ <i>۲</i>	Bridge supply for <u>inp</u> ut <u>2</u>				
ЬгБ.И	<u>Br</u> idge <u>v</u> oltage	5	5 volt bridge supply				
		10	10 volt bridge supply				
SHnE	Calibration <u>sh</u> u <u>nt</u>	Eif	External shunt resistor used				
	resistor	Int	Internal shunt resistor used				
The strair	n gauge transducer mo	dule has a	single input so the above parame	eters are shown	under list <b>-</b> <i>H</i> only		

#### 4.6.12 Transmitter Power Supply

The following parameters appear:-

Module P	arameters	Option	Meaning
<b>, d</b> <u>Id</u> entity of module		EP.SU	<u>T</u> ransmitter <u>p</u> ower <u>su</u> pply
Func	<u>Func</u> tion	попЕ	Fixed 24Vdc 20mA supply

## 4.7 Indicator calibration

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This section explains how to calibrate PV inputs 1 and 2, and retransmission outputs. It should not be confused with User Calibration described in section 3.6 which allows the user to add offsets to compensate for external measurement inaccuracies. Calibration of the indicator should not normally be necessary and must only be carried out using calibrated reference sources. It is always possible to revert to factory calibration settings if necessary.

## 4.7.1 To Calibrate Input 1 or 2

- A mV calibration should be carried out before thermocouple and RTD calibrations.
- Connect a mV, volt source to the input which you wish to calibrate.
- If the input is RTD connect a resistance box.



4.7.1.1 To Calibrate mV or Volt Inputs:-





## 4.7.1.2 To Calibrate CJC

In addition, for thermocouple inputs, calibrate Cold Junction Compensation (CJC), as follows:-



## 4.7.2 To Calibrate Retransmission Output

Connect the retransmission output to a multi-meter set to volts or mV as appropriate.



Figure 4-11: Retransmission output calibration

D	o This	This Is The Display You Should See	Additional Notes		
1.	From the < <b>r</b> c <b>AL</b> > list press ▼ or ▲ as many times as necessary to select the module to be calibrated, e.g. < <b>IAH</b> >	rcAL	In this example module 1 will be calibrated. The high output is calibrated first		
2. 3.	Press to show < <b>CALH</b> > Press or to adjust the required output read on the meter	EALH	The reading on the indicator can be adjusted between -999 and +999. This is an arbitrary value which acts as a trim on the output		
4. 5.	Press to select the <rcal> list Press or as many times as necessary to select the module to be calibrated, e.g. &lt; IALo&gt;</rcal>	rcAL	The low output is calibrated next		
6. 7.	Press to show <[ALL> Press or to adjust the required output read on the meter	-960 CALL	The reading on the indicator can be adjusted between -999 and +999. This is an arbitrary value which acts as a trim on the output		

## 4.7.3 To Restore Factory Calibration

Factory calibration of PV input and PV input 2 can be restored as follows:-

Do This	This Is The Display You Should See	Additional Notes
1. From the < <b>PU</b> > list press ▼ or ▲ as many times as necessary to select < <b>FACL</b> >	FACE PU	The factory set calibration values are restored

#### 4.7.4 Calibration Parameters

EAL
- - ↓

EAL	Basic Indicator Calibration		Selected parameter		
r[AL	Selected <u>r</u> e- <u>cal</u> ibration	попЕ	Idle state - no calibration performed		
	parameter	PU. 1	Main process value input selected		
		PU.2	Second analogue input selected (this will a position 3)	always be in module	
		IR,Hı	Module 1 DC retransmission high output (	if installed)	
		IA.L.o	Module 1 DC retransmission low output (it	f installed)	
		2R.H.	Module 2 DC retransmission high output (	if installed)	
		2RLo	Module 2 DC retransmission low output (i	f installed)	
		JAH	Module 3 DC retransmission high output (	if installed)	
		3RLo	Module 3 DC retransmission low output (i	finstalled)	
IfrEAL	= PU I or PU2 the following parameter	ers	Calibration point	Calibration value	
appear:					
ΡU	<u>PU</u> or <u>PU</u> 2 calibration point	1 dLE	Idle		
		mu.L	mV low calibration point selected	0.000 mV	
		тц.Н	mV high calibration point selected	50.000 mV	
		U D	0 Volt calibration point selected	0.000V	
		U 10	10 Volt calibration point selected	10.000V	
		IL J	Cold junction calibration	See below	
		rEd	Resistance input calibration	400.00Ω	
		HI D	High impedance input. 0 Volt calibration point selected	0.000V	
		HI I.D	High impedance input. 1.0 Volt calibration point selected	1.000V	
		FREF	Restore factory calibration selected		
60	Start calibration	ла	Waiting to calibrate PV point		
		YES	Start calibration		
		Ьобу	Busy calibrating		
		donE	Calibration complete		
		FR, L	Calibration failed		
IfrEAL	= IAH, to IALo (DC output module	calibration	) the following parameters appear:		
cALL	DC output <u>cal</u> ibration <u>l</u> ow point	0	$\square$ = Factory cal. Trim value to give output	= + 1V or +2mA	
cAL H	DC output <u>cal</u> ibration <u>h</u> igh point	0	<b>IDD</b> = Factory cal. Trim value to give outp	out = + 9V or +18mA	

## 4.7.5 Password Configuration

PASS	Passwords	Range	Notes When passwords are changed please make a note of the new numbers	Default setting	Customer setting
ACC P	Full and Edit level password	0- 9999	Having once entered the correct password, operator, full or edit level can be selected at will. To return to operator level and lock the indicator in this level, either switch the indicator off and on again or enter an invalid password as described in section 4.2.1.	1	
cnF.P	Configuration level password	0- 9999	Configuration level can only be entered from the above level. You must exit this level to return to operator level by following the exit procedure in section 4.7.6.	2	
EAL P	User calibration password	0- 9999	User calibration level (described in Section 3.5.1.) can be entered from operator level. To return to normal operation: Enter an incorrect password Switch power off and on again	3	

## 4.7.6 To Leave Configuration Level

D	o This	This Is The Display You Should See	Additional Notes			
1.	Press $\square$ to reach the $\langle E_I, E \rangle$ display	¥ES	After 2 secs the display will blank then			
2.	Press 🔽 or 🔺 to select < <b>YE5</b> >		level			

## 5 Ordering Code

Model	Function	Display	Supply	Module 1	Module 2	Module 3	3 F	Relay	Co	omms	PDS Mardula	Manual		
number		colour	voitage				UL	itput i	IVI	odule	iviodule			
2408 <i>i</i>	<u> </u>										l			
2408i         Function         AL       Indicator/Alarm unit         AP       Profibus Indicator         Bisplay colour       Alarm         G       Green display         M       Display colour         G       Green display         N       Display colour         C       Display colour         D       Cret         Display colour       Cret         D       Cret         N       Supply voltage         VH       230Vac         VL       24Vac/dc         1       -2         .3       .4         will be assigned to relay       .4         output 1 and alarms 2, 3 and 4       .5         Dual r       Dual r			K Module nor arm Relay outg Module fit R Select alarm of C retransmissic Module fit rst character Process Va Setpoint ro Error retra cond characte 0-20mA 4-20mA 0-5Vdc 1-5Vdc 0-10Vdc ual relay (Note	L lules 1, 2 and ot fitted out (change-o ted unconfigu- configuration m ted unconfigu- alue retransm etransmission r 2) ted unconfigu	I 3 wer) ured from table ured ission n	XX N RF F OR Sele from tal Table A Alarm ( See nc Non-la FH DL DL DL DL DL DL DL RA Latchee HA	Relay Output 1         XX       Not fitted         RF       Fitted unconfigured         OR Select alarm configuration         from table A         Table A:         Alarm relay configuration         (See note 1)         Non-latched alarms         FH       High alarm         FL       Low alarm         DB       Deviation band alarm         DL       Deviation high alarm         RA       Rate-of -change alarm         LACthed alarms       HA         Hagh alarm       LA         Low alarm       Low alarm				Comms module XX Module not fitted RS232 Module A2 Module fitted unconfigured A Modbus protocol M AE EI-Bisynch protocol RS485 (2-wire) Module Y2 Module fitted unconfigured YM Modbus protocol YE EI-Bisynch protocol RS485 (4-wire) (= RS422) Module F2 Module fitted unconfigured F4 Modbus protocol F5 EI-Bisynch protocol F6 EI-Bisynch protocol F6 EI-Bisynch protocol F7 Brofibus Module			
Note 2: The	allocation of	T	iple contact in	put (Note 3)		LA	Low alarm		PB High speed RS485					
alarms to the outputs must configuration Note 3: Tripl inputs can be the user for	Imple contact input (Note 3)         to the dual relay         to the dual relay         s must be performed in uration by the customer.         Triple contact input (Note 3)         Triple logic input (Note 3)         TL         Module fitted unconfigured         Triple logic output (Note 4)         TP         Module fitted unconfigured         Triple logic output (Note 4)         Transmitter supply		NW	BD     Deviation band alarm       WD     Deviation low alarm       AD     Deviation high alarm       RT     Rate-of -change alarm       NW     New alarm	rm n m ırm	XX M M6 M RS F	PDS module Aodule not fitt Aodule fitted Inconfigured Remote setpo	ted int input						
functions liste	ed under Digi	ital M	S 24Vdc, 20	mA supply							Manual			
Inputs 1 and 2. Note 4: The triple logic can configured as alarm outputs or as telemetry outputs via digital communications.		utput 1 G G 2 D	rain Gauge Tra & 2 only) (note 3 5V transdu 5 10v transdu 10 analogue in 5 Module fit For config field	nsducer supp 5) Jeer supply lucer supply <b>put</b> (module ted unconfigu juration, see F	<b>bly</b> (modules e 3 only) ured 2V Function	Note 5: I transduce will be in position 3 supply fo position	By default, er supply f stalled in 1 2 and the or input 2 i 1.	the for input module transduce n module	1 er	XXX ENG FRA GER NED SPA SWE ITA	None English French German Dutch Spanish Swedish Italian			

SOFTWARE CONFIGURATION					Con	figuration of 2	2 <sup>nd</sup> analogue inp	out requires D5 i	n module 3	
Sensor Input	Setpoint min	Setpoint max	Display Units	Digital input 1	Digital input 2	2 <sup>nd</sup> DC Input	PV Function	2 <sup>nd</sup> Input Display Min	2 <sup>nd</sup> Input Display Max	Configuration option
	Note 6	Note 6				Note 7		Note 8	Note 8	

Sensor input & 2nd DC input			Setpoint min & max					Display Units		
			•	с	0	F	С		°C K °K	
Thermocouples			Min	Max	Min	Max	F		°F X Blank	
J	Type J		-210	1200	-340	2192				
Κ	Туре К		-200	1372	-325	2500			PV function	
Т	Type T		-200	400	-325	750	X>	×	Input 1 displayed	
L	Type L		-200	900	-325	1650	LC	C	PV = the lowest of i/p 1 and 2	
N	Type N		-250	1300	-418	2370	HI		PV = the highest of i/p 1 and	
R	Type R		-50	1768	-58	3200			2	
S	Type S		-50	1768	-58	3200	FN	1	PV derived from i/p 1 and 2	
В	Type B		0	1820	32	3308	RS	S .	Remote setpoint	
Р	Platinell II		0	1369	32	2496				
Ζ	Pt100		-200	850	-325	1562			Digital inputs 1 & 2	
<b>Process inputs</b> (Scaled to setpoints max & min)			Rang	e Min	Rang	e Max	X	X	Disabled	
F -100 to +100mV			-99	999	99	999	A	C	Alarm acknowledge	
Y 0 to 20mA (note 2)			-99	999	99	999	KL	_	Keylock	
А	4 to 20mA (note 2)		-99	999	99	999	Sh	۲,	Remote setpoint select	
W	0 to 5Vdc		-99	999	99	999	P	<i>.</i>	Select process value input 2	
G	1 to 5Vdc		-99	999	99	999	M	5	CTX mode 5 (digital input 2	
V	0 to 10Vdc		-99	999	99	999			only). For use with PDTCX	
Fa	ctory downloaded input								'smart' current transformer.	
С	Type C -W5%Re/W26%Re	"Table Reference	0 to	2319	32 to	o 4200	J1		Initiate tare correction on	
_	(default downloaded input)	Number"							strain gauge input 1	
D	Type D - W3%Re/W25%Re	"T035"	0 t	0 2399	32 to	4350	J2	2	Initiate tare correction on	
F	F thermocouple	"T012"	-270 t	0 999	-450 t	o 1830			strain gauge input 2	
1	Ni/Ni18%Mo	"T033"	0 t	o 1399	32 t	o 2550	JB	3	Initiate automatic calibration	
2	Pt20%Rh/Pt40%Rh	"T025"	0 t	0 1870	32 t	0 3398			of strain gauge input 1	
3	W/W26%Re (Engelhard)	"T09"	0 t	0 2000	32 t	0 3632	J4	1	Initiate automatic calibration	
4	W/W26%Re (Hoskins)	"T029"	0 t	0 2010	32 t	0.3650			of strain gauge input 2	
5	W5%Re/W26%Re (Engelhard)	"T011"	10 t	0 2300	50 t	o 4172				
6	W5%Re/W26%Re	"T038"	0 t	0 2000	32 t	0 3632			Configuration Option	
-	(Bucose)		0.				XX	X	Standard	
7	Pt10%Rh/Pt40%/Rh	"T023"	200 t	o 1800	392 to	o 3272	SC	3	Load cell/strain gauge	
8	Exergen K80 I.R. Pyrometer	"Er80"	-45 t	o 650	-49 t	o 1202	Μ	Р	pressure transducer	

Note 6: Setpoint min and max: Include the decimal points required in the displayed value.

Note 7: Select the code required from the Sensor Input table.

Note 8: These two fields are used to scale the  $2^{nd}$  DC input if it is a linear process input, otherwise it should be left blank.

Note 9: For mA inputs, a 1% 2.49  $\Omega$  current sense resistor is supplied. For greater accuracy, a 0.1% resistor can be ordered - Part No. SUB2K/249R.1.

## 6 Safety and EMC Information

## Safety

This indicator complies with the European Low Voltage Directive 73/23/EEC, amended by 93/68/EEC, by the application of the safety standard EN 61010.

#### **Electromagnetic compatibility**

This indicator conforms to the essential protection requirements of the EMC Directive 89/336/EEC, amended by 93/68/EEC, by the application of a Technical Construction File. This indicator satisfies the general requirements of the industrial environment defined in EN 50081-2 and EN 50082-2.

#### General

The information contained in these instructions is subject to change without notice. While every effort has been made to ensure the accuracy of the information, your supplier shall not be held liable for errors contained herein.

#### Unpacking and storage

The packaging should contain the indicator, two panel retaining clips, a  $2.49\Omega$  current sense resistor and this instruction leaflet.

If the packaging or the indicator is damaged, do not install the product but contact your supplier.

This indicator has no user serviceable parts. Contact your supplier for repair.

## Caution: Charged capacitors

Before removing the indicator from its sleeve, switch off the supply and wait two minutes to allow capacitors to discharge. Failure to observe this precaution may damage the indicator or cause mild electric shock.

#### Precautions Against Electrostatic Discharge Damage

When the indicator is removed from its sleeve, it is vulnerable to damage by electrostatic. To avoid this, observe anti-static handling precautions.

## Cleaning

Do not use water or water based products to clean labels or they will become illegible. Isopropyl alcohol may be used to clean labels. A mild soap solution may be used to clean other exterior surfaces of the product.

## Safety Symbols

The following safety symbols are used on the controller and in this manual:

\Lambda Caution, important safety information





Useful information or hint

## Personnel

Installation must be carried out by qualified personnel.

#### Enclosure of live parts

The indicator must be installed in an enclosure to prevent hands or metal tools touching parts that may be electrically live.

## Caution: Live sensors

The alarm acknowledge/keylock input is electrically connected to the sensor input (e.g. thermocouple). In some installations the temperature sensor may become live. The indicator is designed to operate under these conditions, but you must ensure that this will not damage other equipment connected to the logic input/output and that service personnel do not touch this connection while it is live. With a live sensor, all cables, connectors and switches for connecting the sensor and non-isolated inputs and outputs must be mains rated.

## Wiring

Wire the indicator in accordance with the wiring data given in these instructions. Take particular care not to connect AC supplies to the low voltage sensor input or logic outputs. Only use copper conductors for connections, (except thermocouple). Ensure that the installation complies with local wiring regulations, and observe maximum voltage safety limits.

## Power Isolation

The installation must include a power isolating switch or circuit breaker that disconnects all current carrying conductors. The device should be mounted in close proximity to the indicator, within easy reach of the operator and marked as the disconnecting device for the indicator.

## Voltage rating

The maximum continuous voltage applied between any connection and ground must not exceed 264Vac.

For the above reason the indicator should not be wired to a three-phase supply with an unearthed star connection. Under fault conditions such a supply could rise above 264Vac with respect to ground and the product would not be safe.

## **Conductive pollution**

Electrically conductive pollution must be excluded from the cabinet in which the indicator is mounted. For example, carbon dust is a form of electrically conductive pollution. Where condensation is likely, for example at low temperatures, include a thermostatically controlled heater in the cabinet.

#### Installation requirements for EMC

- For general guidance refer to EMC Installation Guide, HA025464.
- It may be necessary to fit a filter across the relay output to suppress conducted emissions. The filter requirements will depend on the type of load.

#### Routing of wires

To minimise the pick-up of electrical noise, the sensor input wiring should be routed away from high-current power cables. Where it is impractical to do this, use shielded cables with the shield grounded at both ends.

#### **Technical Specification** 7

## Main process value input and second DC input

	•
Low level range	-100 to +100mV
High level range	0-20mA or 0-10Vdc
Sample rate	9Hz
Resolution	${<}2\mu V$ for low level inputs
	<2mV for high level inputs
Linearity	Better than 0.2°C
Calibration accuracy	<u>+</u> 0.2% of reading, or <u>+</u> 1°C or <u>+</u> 1LSD, whichever is the greater
User calibration	Low and high offsets can be applied
Input filtering	OFF to 999.9 seconds
Thermocouple types	Refer to ordering code sensor input table
Cold junction compensation	In automatic mode, >30:1 rejection of ambient temperature change.
3-wire Pt100 input Bulb current:	0.3mA
Maximum lead resistance	Up to $22\Omega$ in each lead without error
2 <sup>nd</sup> analogue input functions	2 <sup>nd</sup> process value, remote setpoint, select min, select max, derived value
Input impedance, mV inputs	>10MΩ
Input impedance, Volt inputs	>69ΚΩ
Digital inputs	
Contact closure or open	collector inputs
Note: These are powered by the	controller
Digital inputs 1 & 2	Switching voltage/current:
(Non isolated from PV)	

Triple contact closure inputs

Isolated. Specification as dig. inputs 1 & 2

On state resistance >28K $\Omega$ 

## **Externally powered inputs**

Triple logic inputs	Off state:	<5Vdc
	On state:	10.8 to 30Vdc @ 2.5mA

## **Digital input functions**

As per digital inputs 1 & 2 in the ordering code

## **Digital outputs**

Relay rating	2A, 264Vac resistive
Triple logic output	8mA, 12Vdc per channel
Digital output functions	as per the ordering code
DC retransmission	
Range	Scaleable between 0-20mA and 0- 10Vdc
Resolution	1 part in 10,000
Retransmission values	Process value, setpoint or error

from

## **Transmitter supply** Rating Strain

Rating	20mA, 24Vdc
Strain gauge bridge s	upply
Bridge voltage	Software selectable, 5 or 10Vdc
Bridge resistance	$300\Omega$ to $10K\Omega$
Internal shunt resistor	30.1K $\Omega$ at 0.25%, used for calibration of 350 $\Omega$ bridge
Alarms	
Number of alarms	Four
Alarm types	High, low, deviation high, deviation low, deviation band, rate of change in units/sec, rate of change in units/min, new alarm status. Sensor break alarm
Alarm modes	Latching or non-latching. Blocking Energised or de- energised in alarm
Alarm delay	OFF to 999.9 seconds
Communications	
Module types	RS232, 2-wire RS485 and 4- wireRS485
Protocols	Modbus® or El-Bisynch (ASCII)
	Devicenet
	Profibus
PDS	
Functions	Remote setpoint input from master controller
General	
Display colour	Red or green options
Number of digits	Five with up to three decimal places
Supply	100 to 230Vac <u>+</u> 15%, 48 to 62Hz
	or 24Vac, 48 to 62Hz, -15%+10% or 24 Vdc -15%+20%
Power consumption	15W max
Operating ambient	0 to 55°C and 5 to 95% RH non- condensing
Storage temperature	-10 to +70°C
Panel sealing	IP65, NEMA12
Dimensions	96W x 48H x 150D
Weight	400g max
EMC Standards:	EN50081-2 & EN50082-2 generic standards for industrial environments
Safety standards	Meets EN 61010, Installation category II, pollution degree 2.
Atmospheres	Not suitable for use above 2000m or in explosive or corrosive atmospheres

Engineering Manual

#### www.eurotherm.com herm: Internation

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